

Optimal Exploration is no harder than Thompson Sampling

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Abstract

This paper proposes a computationally efficient algorithm for pure exploration in linear bandits by leveraging sampling and argmax oracles. Given a set of arms $\mathcal{Z} \subset \mathbb{R}^d$, the pure exploration linear bandit problem aims to return $\arg \max_{z \in \mathcal{Z}} z^\top \theta_*$, with high probability through noisy measurements of $x^\top \theta_*$ with $x \in \mathcal{X} \subset \mathbb{R}^d$. Existing (asymptotically) optimal methods scale in the size of $|\mathcal{Z}|$ by requiring either a) potentially costly projections for each arm $z \in \mathcal{Z}$ or b) explicitly maintaining a subset of \mathcal{Z} under consideration at each time. In general, computing projections may be computationally expensive, and maintaining a subset of \mathcal{Z} may be unfeasible in many combinatorial settings. Our approach overcomes both of these limitations by resorting to *sampling* from an appropriate distribution over possible parameters combined with access to an argmax oracle. In this vein, it enjoys a similar computational efficiency of Thompson Sampling. However, unlike Thompson Sampling, which is known to be sub-optimal for pure exploration, our algorithm provably guarantees an exponential convergence rate with the exponent being the optimal among all possible allocations asymptotically.

1 Introduction

The pure exploration bandit problem considers a sequential game between a learner with two set of arms $\mathcal{X}, \mathcal{Z} \subset \mathbb{R}^d$ and nature. In each round, the learner chooses an arm $x \in \mathcal{X}$ and observes a noisy stochastic reward $y = x^\top \theta_* + \epsilon$ where $\theta_* \in \Theta$ is an unknown parameter vector and ϵ is assumed to be i.i.d Gaussian noise. The goal of the learner is to identify $z_* = \arg \max_{z \in \mathcal{Z}} z^\top \theta_*$ with high probability in few measurements. The case of $\mathcal{X} = \mathcal{Z}$ is a natural case to consider, and has enjoyed a fair amount of attention [29, 9, 7]. Notably, these algorithms share a common trait - complexity. Each necessitates the resolution of convex programs at every iteration. Consequently, it prompts us to question: is such complexity indeed indispensable for reaching asymptotic optimality?

Maintaining our focus on the specific instance where $\mathcal{X} = \mathcal{Z}$, we note that the pure-exploration task can be addressed using any readily available regret minimization algorithm. That is, if an algorithm generates a series of plays $\{x_t\}_{t=1}^T$ such that $\max_{x \in \mathcal{X}} \sum_{t=1}^T \langle \theta_*, x - x_t \rangle \leq d\sqrt{T}$ then this immediately implies that \hat{x}_T drawn uniformly from the set $\{x_t\}_{t=1}^T$ is equal to $x_* = \arg \max_{x \in \mathcal{X}} \langle x, \theta_* \rangle$ with constant probability as soon as $T \geq d^2/\Delta_{\min}^2$, where $\Delta_{\min} = \min_{x \in \mathcal{X}, x \neq x_*} \theta_*^\top (x^* - x)$. One popular regret-minimization algorithm is Thompson Sampling (TS). Following its re-emergence from nearly seven decades of relative obscurity, it has rapidly ascended to become the most prevalently

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applied bandit algorithm in practical scenarios, as per the industrial experience of the authors. We postulate that its popularity is due to (1) its simplicity to implement, (2) its flexibility to encode side-information in its prior, (3) its computational efficiency, and (4) strong empirical performance. The algorithm works by maintaining a distribution p_t over Θ given all observations up to the time t , and then plays $x_t = \arg \max_{x \in \mathcal{X}} \langle x, \theta_t \rangle$ where $\theta_t \sim p_t$. Once $y_t = \langle x_t, \theta_* \rangle + \epsilon_t$ is observed the distribution is updated and the process repeats. Unfortunately, TS is known to be sub-optimal for the pure exploration linear bandits problem due to its greedy exploration strategy. Indeed, there exist instances of \mathcal{X} and θ_* for which the sample complexity of TS to identify the best arm scales *quadratically* in the optimal sample complexity achieved by other algorithms [29]. Even for regret minimization, it is known that TS is far from optimal from an instance-dependent perspective [17]. But yet, due to its many favorable properties it is still the go-to algorithm in practice.

This paper has a simple but ambitious goal: make an algorithm that is (1) as easy to implement, (2) as flexible to encode side-information, and (3) as computationally efficient as Thompson sampling, but match the asymptotic optimal sample complexities of the best pure exploration algorithms. We achieve this goal by not striving too far from the Thompson sampling algorithm itself. In fact, our proposed algorithm can be viewed as a generalization of Top Two Thompson Sampling for the standard multi-armed bandit game [26] to the richer linear setting. We maintain a sampling distribution p_t centered at $\hat{\theta}_t$ (a regularized least squares estimator computed after t samples), and repeatedly sample $\theta_t \sim p_t$ until $\arg \max_{z \in \mathcal{Z}} \langle z, \theta_t \rangle$ is distinct from $\hat{z}_t = \arg \max_{z \in \mathcal{Z}} \langle z, \hat{\theta}_t \rangle$. Once such a θ_t is found, we updated an online learner maintaining a distribution over \mathcal{X} with rewards $r_x := \|\theta_t - \hat{\theta}_t\|_{xx^\top}^2$. At each time we sample an x_t from the distribution maintained by the online learner. We prove that $\mathbb{P}(\hat{z}_t \neq z_*)$ decreases at an exponential rate, with an optimal exponent among all possible fixed budget allocations.

1.1 Problem Setting and Notation

We first define the linear bandit setting. Let $\mathcal{X}, \mathcal{Z} \in \mathbb{R}^d$ be two sets of arms and $\Theta \subset \mathbb{R}^d$ be the parameter space. At time t , we draw an action $x_t \in \mathcal{X}$, and receive the reward $y_t = x_t^\top \theta_* + \epsilon_t$ where $\theta_* \in \Theta$ and ϵ_t is i.i.d. Gaussian noise. The choice of arm x_t at time t is dependent on the filtration generated by $\{(x_s, y_s)\}_{s=1}^{t-1}$; furthermore, we denote the probability law determined by this filtration be \mathbb{P}_θ .

Goal: We are interested in the best-arm identification task, i.e. we would like to find $z_* := \arg \max_{z \in \mathcal{Z}} z^\top \theta_*$ with high probability, while minimizing the number of measurements taken in \mathcal{X} .

We make the following assumption on the parameters that we will discuss further in Section 3.1.

Assumption 1. Θ is closed, and bounded, with a non-empty interior.

Assumption 2. Assume that $\max_x \|x\|_2 \leq L$.

Assumption 3. Assume that $\text{span}(\mathcal{Z}) \subset \text{span}(\mathcal{X})$ and the optimal arm $z_* \in \mathcal{Z}$ is unique.

Notation. For any matrix $A \in \mathbb{R}^{n \times n}$, we define the norm $\|x\|_A^2 := x^\top A x$. Given a set \mathcal{S} , we define the simplex $\triangle_{\mathcal{S}} := \{\lambda \in \mathbb{R}_{\geq 0}^{|\mathcal{S}|} : \sum_{i=1}^{|\mathcal{S}|} \lambda_i = 1\}$. Finally, given a (multivariate) normal distribution $\mathcal{N}(\theta, \Sigma^{-1})$ on \mathbb{R}^d and some set Θ , we define the truncated normal distribution, denoted as $\text{TN}(\theta, \Sigma^{-1}; \Theta)$, to be the normal distribution restricted on Θ . For some $\lambda \in \triangle_{\mathcal{X}}$, we define $A(\lambda) := \sum_{x \in \mathcal{X}} \lambda_x x x^\top$. We define $\Delta_{\max} := \max_{x \in \mathcal{X}} \max_{\theta, \theta' \in \Theta} |x^\top (\theta - \theta')|$. In some round t , we

define $\hat{\theta}_t = V_{t-1}^{-1} S_{t-1}$ where $V_t = \sum_{s=1}^t x_s x_s^\top$ and $S_t = \sum_{s=1}^t x_s y_s$. We define the constants used in the algorithm as $C_{3,\ell} = \Delta_{\max} + L^2 \sqrt{d \log(T_\ell \ell^2)}$. The precise definition is in the Appendix.

2 Motivating Our Approach

Among all adaptive algorithms, it is known that for every $\theta_* \in \Theta$ there exists a $\lambda \in \Delta_{\mathcal{X}}$ such that sampling x_1, x_2, \dots IID from λ achieves the optimal sample complexity in the fixed confidence setting [29, 9, 7], in which we would like to find an arm with probability $1 - \delta$ of being optimal given a confidence level δ . Specifically, for any $\Theta \subset \mathbb{R}^d$ and $\mathcal{X}, \mathcal{Z} \subset \mathbb{R}^d$ define

$$\tau^* := \max_{\lambda \in \Delta_{\mathcal{X}}} \min_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta_*\|_{A(\lambda)}^2 \quad (1)$$

where $\Theta_{z_*}^c = \{\theta \in \Theta : \exists z \in \mathcal{Z}, z^\top \theta \geq z_*^\top \theta\}$. Then it is known that to identify z_* with probability at least $1 - \delta$, the expected sample complexity of any algorithm scales as $(\tau^*)^{-1} \log(2.4/\delta)$. Moreover, sampling according to the λ that achieves the maximum, when paired with an appropriate stopping time, achieves the optimal sample complexity asymptotically. As our setting is more naturally analyzed in the so-called fixed budget setting, we next state a result that can be viewed as a generalization of the result of [26] originally stated for the multi-armed bandit setting. Note that this is not a lower bound for the fixed budget setting, since we only allow fixed λ not adapting to the observations.

Theorem 2.1. *Fix $\Theta = \mathbb{R}^d$ and any $\theta_* \in \Theta$. For some λ consider a procedure that draws $x_1, \dots, x_T \sim \lambda$, then observes $y_t = \langle x_t, \theta_* \rangle + \epsilon_t$ with $\epsilon_t \sim \mathcal{N}(0, 1)$, and then computes $\hat{z}_T = \arg \max_{z \in \mathcal{Z}} \langle z, \hat{\theta}_T \rangle$ where $\hat{\theta}_T = \arg \min_{\theta \in \Theta} \sum_{t=1}^T \|y_t - \langle \theta, x_t \rangle\|_2^2$. Then for any $\lambda \in \Delta_{\mathcal{X}}$ we have*

$$\limsup_{T \rightarrow \infty} -\frac{1}{T} \log \left(\mathbb{P}_{\theta_*, x_t \sim \lambda} (\hat{z}_T \neq z_*) \right) \leq \tau^*.$$

The quantity τ^* is naturally interpreted from a hypothesis-testing lens. Given a fixed sampling distribution λ , note that $\mathbb{E}_{x \sim \lambda} KL(\mathcal{N}(\theta^\top x, 1) \| \mathcal{N}(\theta_*^\top x, 1)) = \frac{1}{2} \|\theta - \theta_*\|_{A(\lambda)}^2$. Thus the min-max problem above aims to construct the distribution λ which maximizes the smallest KL divergence between θ and any alternative with a different best-arm. As noticed by many authors, this can be translated into a game-theoretic language. The max-player chooses a distribution over the set of possible measurements \mathcal{X} . At the same time the min-player chooses an alternative θ whose best arm is not z_* in an attempt to fool the λ -player. This lower bound intuitively suggests a strategic course of action for algorithm designers: devise a sampling method that ensures the resultant allocation aligns with the aforementioned objective.

In this pursuit (discussed extensively in related works, Section 4) this game theoretic perspective has been directly exploited by several works in the past to give asymptotically optimal algorithms. The approaches of these works differ in detail but are similar in spirit and are motivated by the following oracle strategy that has access to θ_* . At each time, the max-player utilizes a no-regret online learner, such as exponential weights [3], to set λ_{t+1} based on an estimate of the best-response of the min-player, namely $\min_{\theta \in \Theta_{z_*}^c} \|\theta - \theta_*\|_{A(\lambda_t)}^2$. This guarantees that

$$\frac{1}{T} \max_{\lambda \in \Delta_{\mathcal{X}}} \min_{\theta \in \Theta_{z_*}^c} \|\theta - \theta_*\|_{A(\lambda)}^2 - \frac{1}{T} \sum_{t=1}^T \min_{\theta \in \Theta_{z_*}^c} \|\theta - \theta_*\|_{A(\lambda_t)}^2 \leq o(1)$$

which by a standard Jensen's inequality argument is sufficient to ensure that $\frac{1}{T} \sum_{t=1}^T \lambda_t$ is an approximate solution to the original saddle point problem. Then, the arm x_t pulled is sampled from λ_t at each time (or a deterministic tracking strategy is used).

The main computational challenge in this approach is that obtaining the best-response can be rather involved. The alternative set can be decomposed as a union of intersections of a convex set with a halfspace: $\Theta_{z_*}^c = \cup_{z \neq z_*} \Theta \cap \{\theta \in \mathbb{R}^d : z^\top \theta \geq z_*^\top \theta\}$. Thus computing the best-response involves computing $|\mathcal{Z}|$ -many projections onto convex sets. For small values of $|\mathcal{Z}|$, this may be feasible. However, if $|\mathcal{Z}|$ is large or the projection step is very expensive, this computation may be onerous. We remark that several recent works have explored eliminating subsets of \mathcal{Z} which can not potentially contain the best-arm [9, 31, 34]. However this still leads us to our fundamental question, “Is there an algorithm that is asymptotically optimal which does not need to explicitly maintain \mathcal{Z} and avoids projection?” We now answer this in the affirmative.

Our method is based on the following equivalent formulation of τ^* . By linearizing the min over alternatives with a distribution over $\Theta_{z_*}^c$, we can apply Sion's minimax theorem:

$$\begin{aligned} \max_{\lambda \in \Delta_{\mathcal{X}}} \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta_*\|_{A(\lambda)}^2 &= \max_{\lambda \in \Delta_{\mathcal{X}}} \min_{p \in \Delta(\Theta_{z_*}^c)} \mathbb{E}_{\theta \sim p} \left[\frac{1}{2} \|\theta - \theta_*\|_{A(\lambda)}^2 \right] \\ &= \min_{p \in \Delta(\Theta_{z_*}^c)} \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim p} \left[\frac{1}{2} \|\theta - \theta_*\|_{A(\lambda)}^2 \right], \end{aligned}$$

where $\Delta(\Theta_{z_*}^c)$ denotes the set of distribution over the alternative set $\Theta_{z_*}^c$. This replaces the projections with an expectation over a distribution on $\Theta_{z_*}^c$. At first glance, the situation may seem worse - we have gone from finitely many projections to needing to maintain a distribution over a potentially infinite set! However, for a minute imagine that Θ is finite and that we solve this saddle-point problem by maintaining a no-regret learner for the max-player as before, while similarly maintaining a no-regret learner for the min-player. Standard results in convex optimization guarantee that the average of the iterates of the two learners converge to a saddle point eventually [22]. To be more precise, at each round t we draw an $x_t \sim \lambda_t$ and feed the (stochastic) loss $\sum_{\theta \in \Theta_{z_*}^c} p_{t,\theta} \|\theta - \theta_*\|_{x_t x_t^\top}^2$ to the learner for the min-player. Assuming the min-player learner is exponential weights, then the update is

$$p_{t+1,\theta} \propto p_{t,\theta} e^{-\eta \|\theta_* - \theta\|_{x_t x_t^\top}^2} \propto e^{-\eta \|\theta_* - \theta\|_{\sum_{s=1}^t x_s x_s^\top}^2}.$$

where η is an appropriate step-size. Hence, the resulting distribution $p_{t+1,x}$ is reminiscent of the probability density function of a multivariate normal distribution $N(\theta_*, \eta^{-1} (\sum_{s=1}^t x_s x_s^\top)^{-1})$ restricted to $\Theta_{z_*}^c$. This observation motivates our algorithm - for the min-player we maintain an appropriate normal distribution and at each round, use samples from this distribution to generate a stochastic loss to feed the max-player. *This approach avoids explicitly maintaining \mathcal{Z} or ever needing to compute a projection!* Of course, this discussion has relied on knowledge of θ_* and z_* . In the next section, we explain how our algorithm, PEPS, overcomes these restrictions.

3 Best Arm Identification Through Sampling

Our main method PEPS is presented in Algorithm 1. Given a budget of T samples, we repeatedly sample $\theta_t \sim p_t$ until the best-arm of $\arg \max_{z \in \mathcal{Z}} z^\top \theta_t$ is not our current best guess

Algorithm 1 Pure Exploration with Projection-Free Sampling (PEPS)

Input: Finite set of arms $\mathcal{X} \subset \mathbb{R}^d$, $\mathcal{Z} \subset \mathbb{R}^d$, time horizon T , $\eta_\lambda, \eta_p, \alpha$

- 1: Define $\lambda^G = \arg \min_{\lambda \in \Delta_{\mathcal{X}}} \max_{x \in \mathcal{X}} \|x\|_{A(\lambda)^{-1}}^2$, $\lambda_1 = \frac{1}{|\mathcal{X}|} \mathbf{1}$
 - 2: Initialize $V_0 = I$, $S_0 = 0$, $p_1 = N(0, V_0)$, $\hat{\theta}_1$ arbitrarily
 - 3: **for** $t = 1, 2, \dots, T$ **do**
 - 4: $\gamma_t = t^{-\alpha}$
 - 5: //Top Two Sampling
 - 6: Compute $\hat{z}_t = \arg \max_{z \in \mathcal{Z}} z^\top \hat{\theta}_t$
 - 7: **repeat**
 - 8: Sample $\theta_t \sim p_t$
 - 9: **until** $\arg \max_{z \in \mathcal{Z}} z^\top \theta_t \neq \hat{z}_t$, equivalently $\theta_t \in \Theta_{\hat{z}_t}^c$
 - 10:
 - 11: //Take Sample and Observe Reward
 - 12: sample $x_t \sim \tilde{\lambda}_t$ where $\tilde{\lambda}_t = (1 - \gamma_t)\lambda_t + \gamma_t\lambda^G$
 - 13: Observe $y_t = \langle \theta_*, x_t \rangle + \epsilon_t$ where $\epsilon_t \sim \mathcal{N}(0, 1)$
 - 14: Update $V_t = V_{t-1} + x_t x_t^\top$, $S_t = S_{t-1} + x_t y_t$, and $\hat{\theta}_{t+1} = V_t^{-1} S_t$
 - 15:
 - 16: //Update Sampling Distributions
 - 17: Update $\lambda_{t+1} \propto \lambda_t e^{\eta_\lambda \tilde{g}_t}$ where $\tilde{g}_{t,x} = \left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2, \forall x \in \mathcal{X}$
 - 18: Update $p_{t+1} = N(\hat{\theta}_{t+1}, \eta_p^{-1} V_t^{-1})$
 - 19: **end for**
 - 20: **repeat**
 - 21: Sample $\tilde{\theta} \sim N(\hat{\theta}_{T+1}, V_T^{-1})$
 - 22: **until** $\tilde{\theta} \in \Theta$
 - Output:** $\arg \max_{z \in \mathcal{Z}} z^\top \tilde{\theta}$
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$\hat{z}_t = \arg \max_{z \in \mathcal{Z}} z^\top \hat{\theta}_t$. We then sample an $x_t \sim \tilde{\lambda}_t$ where $\tilde{\lambda}_t$ is the distribution λ_t maintained by the λ -learner at time t mixed in with a diminishing amount γ_t of the G -optimal distribution λ^G . After playing x_t and observing a reward y_t , PEPS updates both the λ_t and p_t learner. Algorithm 1 depends on a finite time horizon T . To ensure that our algorithm is anytime and eventually converges to the optimal sampling scheme, we employ an outer loop Algorithm 2 utilizing a doubling scheme. Before we explain the theoretical guarantees of this procedure, we first detail some of the aspects of the algorithm.

Updating the sampling distribution for p_t . Our main innovation is introducing a distribution over $\Theta_{\hat{z}_t}^c$ from which we can sample over. We set $p_t = N(\hat{\theta}_t, \eta_p V_{t-1}^{-1})$, and as described utilize rejection sampling to keep sampling a θ_t until $\theta_t \in \Theta_{\hat{z}_t}^c$. Denoting by $p_t(\Theta_{\hat{z}_t}^c)$ the distribution of θ_t , we see that it is a *truncated normal distribution* with support $\Theta_{\hat{z}_t}^c$, i.e. $p_t(\Theta_{\hat{z}_t}^c) = \text{TN}(\hat{\theta}_t, \eta_p V_{t-1}^{-1}; \Theta_{\hat{z}_t}^c)$ [4].

Following the discussion in the Section 2, it is tempting to see this update as a form of continuous exponential weights [3]. However, this is not quite true since the underlying action set $\Theta_{\hat{z}_t}^c$ is changing each round. Note that similar to previous works, we could have maintained a learner for

Algorithm 2 Doubling trick

Input: Finite set of arms $\mathcal{X} \subset \mathbb{R}^d$, $\mathcal{Z} \subset \mathbb{R}^d$

1: **for** $l = 0, 1, \dots$ **do**

2: Set $T_\ell = 2^\ell$, $\eta_\lambda = \sqrt{\frac{\log |\mathcal{X}|}{C_{3,\ell}^2 T_\ell}}$, $\eta_p = \sqrt{\frac{d \log(T_\ell C_{3,\ell})}{C_{3,\ell}^2 T_\ell}}$, $\alpha = 1/4$

3: $\hat{z}_\ell = \text{PEPS}(\mathcal{X}, \mathcal{Z}, T_\ell, \eta_\lambda, \eta_p, \alpha)$

4: **end for**

Output:

each $z \in \mathcal{Z}$ [7]. However, our approach of maintaining a distribution and then restricting it to the considered action set each round prevents the need for this additional complexity of enumerating \mathcal{Z} .

From the perspective of exponential weights, η_p is a step size: the dependence on d in the numerator comes from the dimension of Θ ; and $C_{3,\ell}^2$ is an upper bound on the stochastic loss $\|\theta_t - \hat{\theta}_t\|_{x_t x_t^\top}^2$ that we guarantee with high probability due to forced exploration and boundedness of Θ .

We have the following regret guarantee:

Lemma 3.1 (informal). *In round T_ℓ of epoch ℓ of Algorithm 2, we have with probability greater than $1 - 1/\ell^2$,*

$$\left[\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \theta_* \right\|_{V_{T_\ell}}^2 \right] \leq O(d\sqrt{T_\ell} \log(LT_\ell))$$

Finally we remark that sampling from truncated univariate or multivariate normal distributions is a well-explored practice across statistics and machine learning. A variety of efficient methods such as Gibbs and rejection sampling procedures are available for this purpose and we refer to [8, 23, 20].

Update for λ_t . To update λ_t , which corresponds to the action of our max-player, we employ an exponential weighted learner (Hedge) over the set of actions \mathcal{X} . The reward vector $\tilde{g}_t \in \mathbb{R}^{|\mathcal{X}|}$ is stochastic with expectation $\mathbb{E}_{\tilde{g}_t, x} = \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_t}^c)} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2$ conditional on the history of the algorithm $\{(x_s, y_s, \theta_s)\}_{s=1}^{t-1}$, and is bounded in high probability. We show that if we choose the mixing amount $\alpha = \frac{1}{4}$ and let $\tilde{\Delta}_{\max}$ be an upper bound on the loss function, we have the following regret guarantee:

Lemma 3.2 (informal). *In round T_ℓ of epoch ℓ of Algorithm 2, we have with probability greater than $1 - 1/\ell^2$,*

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_t}^c)} \left\| \theta - \hat{\theta}_t \right\|_{A(\lambda)}^2 - \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_t}^c)} \left\| \theta - \hat{\theta}_t \right\|_{A(\lambda_t)}^2 \leq O\left(\sqrt{(d + \tilde{\Delta}_{\max}) T_\ell \log \ell}\right).$$

Forced Exploration with G-optimal Design. To ensure adequate sampling in all directions, in each round we mix in some amount of the G -optimal distribution, denoted as $\lambda^G := \arg \min_{\lambda \in \Delta_{\mathcal{X}}} \max_{x \in \mathcal{X}} \|x\|_{A(\lambda)^{-1}}^2$. This ensures that $\max_{x \in \mathcal{X}} \|\hat{\theta}_t - \theta\|_{xx^\top}$ is bounded for any $\theta \in \Theta$ and \hat{z}_t is eventually z_* with probability 1. The rate at which the mixture of this distribution decays

as $t^{-\alpha}$, for any $0 < \alpha < 1/2$, so it has no effect on asymptotic performance. We note that thanks to the implicit anti-concentration properties of sampling θ_t from a multivariate Gaussian, this step is probably unnecessary and just an artifact of the analysis.

Argmax Oracle One advantage of our approach that is most reminiscent of Thompson Sampling is the calculation of \hat{z}_t at the start of each epoch using a sample from the distribution $N(\hat{\theta}_t, \eta_p^{-1} V_{t-1}^{-1})$. In practice, if we have an efficient arg max-oracle, this calculation can be computationally efficient and does not require maintaining \mathcal{Z} . By exploiting arg max oracles, we can tractably solve problems like shortest-path and matchings, even in settings where $|\mathcal{Z}|$ is super-exponential in d [14].

Doubling Trick As presented, the regret guarantee for λ_T and p_t requires fixed step sizes η_λ, η_p . To overcome this need for a fixed step size, we use a doubling trick, we restart the algorithm every 2^ℓ samples [28]. We believe the use of the doubling trick is purely a theoretical restriction and a more careful analysis could provide an anytime algorithm with no restarts.

3.1 Theoretical Guarantees

Our main result is the following guarantee on Algorithm 2.

Theorem 3.3. *With probability 1,*

$$\lim_{\ell \rightarrow \infty} -\frac{1}{T_\ell} \log \mathbb{P}_{\theta \sim \pi_\ell}(\hat{z}_\ell \neq z_*) = \tau^*.$$

where $\pi_\ell := N(\hat{\theta}_{T_\ell}, V_{T_\ell}^{-1})$ restricted to Θ .

Thus our algorithm guarantees that asymptotically the probability that we do not identify the optimal arm decays at the rate of $e^{-T\tau^*}$, with τ^* being the optimal exponent as given in Theorem 2.1. Such guarantees on the probability of a sampled arm are similar to those in the Bayesian best-arm literature, namely [26, 11]. In these works, a posterior distribution is maintained and they guarantee that the posterior probability that a non-optimal arm is sampled converges at an exponential rate, with the best possible exponent among all allocation rules. We provide a similar guarantee here for linear bandits. We provide a small sketch of the proof now. A full proof will be provided in the Appendix.

Proof sketch. We say that $a_n \doteq b_n$ if $\frac{1}{n} \log(a_n/b_n) \rightarrow 0$ as $n \rightarrow \infty$. We focus on a fixed round ℓ of Algorithm 2. Using the fact that the expectation of the empirical log-likelihood ratio (conditioned on the data collected) between θ_* and some $\theta \in \Theta$ is the KL divergence between them, we can show using a Laplace Approximation

$$\mathbb{P}_{\theta \sim \pi_\ell}(\hat{z}_\ell \neq z_*) \doteq \exp \left(-T_\ell \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta_*\|_{A(\bar{e}_{T_\ell})}^2 \right).$$

where $\bar{e}_{T_\ell} = \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} e_{x_t}$. Letting $\bar{p}_{T_\ell} = \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} p_t(\Theta_{\hat{z}_t}^c)$, we have

$$\begin{aligned}
& \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\lambda)}^2 \right] - \min_{p \in \Delta(\Theta_{z_*}^c)} \mathbb{E}_{\theta \sim p} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\bar{e}_{T_\ell})}^2 \right] \\
&= \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_t}^c)} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\lambda)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_t}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\lambda_t)}^2 \right] \\
&\quad \text{(regret for max learner)} \\
&+ \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{\hat{z}_t}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\lambda_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] \quad \text{(error when } \hat{z}_t \neq z_*) \\
&+ \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \theta_* \right\|_{V_{T_\ell}}^2. \quad \text{(regret for the min learner)}
\end{aligned}$$

The regret guarantees for λ and p 's in Lemmas 3.2 and 3.1 ensure the first and third sum are $o(1)$ and so go to 0 as $T_\ell \rightarrow \infty$. The fact that $p_t(\Theta_{\hat{z}_t}^c)$ is equal to $p_t(\Theta_{z_*}^c)$ for large enough t , ensures that the middle term similarly goes to 0. Combining all terms and the fact that $\hat{\theta}_t$ is close to θ_* guarantees that for any $\epsilon > 0$ there is a sufficiently large ℓ such that

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\left\| \theta_* - \theta \right\|_{A(\lambda)}^2 \right] - \min_{p \in \Delta(\Theta_{z_*}^c)} \mathbb{E}_{\theta \sim p} \left[\left\| \theta_* - \theta \right\|_{A(\bar{e}_{T_\ell})}^2 \right] \leq \epsilon$$

which implies that $\inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \left\| \theta - \theta_* \right\|_{A(\bar{e}_{T_\ell})}^2 \geq \max_{\lambda \in \Delta_{\mathcal{X}}} \min_{p \in \Delta(\Theta_{z_*}^c)} \mathbb{E}_{\theta \sim p} \left[\left\| \theta_* - \theta \right\|_{A(\lambda)}^2 \right] - \epsilon$. Since the first term on the right-hand side is τ^* , we have shown that $\inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \left\| \theta - \theta_* \right\|_{A(\bar{e}_{T_\ell})}^2 \geq \tau^* - \epsilon$. Since by definition $\tau^* \geq \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \left\| \theta - \theta_* \right\|_{A(\bar{e}_{T_\ell})}^2$, choosing $\epsilon \rightarrow 0$ concludes the proof that

$$\mathbb{P}_{\theta \sim \pi_\ell}(\hat{z}_\ell \neq z_*) \doteq \exp \left(-T_\ell \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \left\| \theta - \theta_* \right\|_{A(\bar{e}_{T_\ell})}^2 \right) = \exp(-T_\ell \tau^*).$$

□

Remark: Stopping times. Note that we are not providing a guarantee on the expected stopping time for any finite δ . Existing asymptotically optimal approaches which guarantee a finite stopping time in high probability, e.g. [7], utilize a generalized log-likelihood-ratio test of the form

$$\max_{z \in \mathcal{Z}} \min_{\theta \in \Theta_{z_t}^c} \left\| \theta - \hat{\theta}_t \right\|_{V_t} \geq \beta(t, \delta)$$

where $\beta(t, \delta) = O(\sqrt{d \log((T + \|\theta_*\|_2)/\delta)})$ is an anytime confidence bound controlling the deviations of $\|\theta - \hat{\theta}_t\|_{V_t}$ [1]. As a result, they can guarantee that their algorithms saturate the lower bound for an expected stopping time, i.e. $\limsup_{\delta \rightarrow \infty} \mathbb{E}[\tau_\delta] / \log(1/\delta) \leq (\tau^*)^{-1}$. Unfortunately, this GLRT stopping rule itself requires a projection onto each element of \mathcal{Z} . We leave it as an open question whether an algorithm can be developed which is asymptotically optimal, requires no explicit projection, and has a finite expected stopping time in high probability.

Remark: Bounded assumptions on Θ . We recall that we assume Θ is closed and bounded. The boundedness assumption is needed since we would like to control that for each $\theta \in \Theta$, the rewards $x^\top \theta$ to be bounded for all arms $x \in \mathcal{X}$, which is used in our analysis of the regret of each learner. Learning algorithms such as AdaHedge [5] avoid the need for bounded rewards and we leave it as a future research direction to remove this condition.

4 Related Work

Pure Exploration Linear Bandits The pure exploration linear bandit problem was introduced in the seminal work of Soare et al [29]. In recent years, there has been renewed interest in this problem due to its ability to capture many best-arm-identification and pure exploration settings. Following the experimental design approach first considered by [29], several different algorithmic frameworks were considered [30, 33, 13].

One of the first algorithms to achieve matching instance-optimal upper and lower bounds (within logarithmic factors) for the case of \mathbb{R}^d was by [9] and depends on an elimination scheme. Shortly after, several works proposed asymptotically optimal algorithms. The first of these methods utilized the track and stop approach given in [10], which fully solves the τ^* objective of Equation 1 using a plug-in estimator $\hat{\theta}_t$ at each round. Due to the computational difficulty of this, several works proposed alternatives that iteratively updated the sampling distribution in each round. This includes the game theoretic viewpoint we utilize first proposed by [7, 6], and a novel modification of Frank-Wolfe by [32]. Other works have augmented these approaches by providing elimination schemes to reduce the set of alternative \mathcal{Z} that need to be considered each round. [34] proposes a hybrid approach combining the elimination from [9] and [7] to remove the condition that Θ needs to be bounded. [31] provide an elimination approach where they carefully exploit properties of \mathcal{Z} . Finally, we mention that the pure exploration problem has also been considered in the generalized linear bandit (logistic) settings in [15, 12]. Future work could explore extending sampling methods to these settings.

Computationally-Efficient Oracle Based Approaches As discussed before, if \mathcal{Z} is a large or combinatorial set, it may be impossible to maintain and appropriate oracles need to be used. [14] considers the linear combinatorial setting for matroid-like classes e.g. shortest-path, top-k, and bipartite matching. By exploiting ideas similar to [9], they provide an algorithm which utilizes the argmax oracle to achieve almost optimal sample complexity. A recent work by [21] reduces optimal policy learning in agnostic contextual bandits to pure exploration, and provides a method analogous to [2] which only relies on cost-sensitive classification oracles.

Bayesian Methods Our approach is perhaps most reminiscent of the Top-Two Thompson Sampling (TTTS) algorithm for best-arm identification in multi-armed bandits of [26]. Similar to Thompson sampling [27], TTTS maintains a posterior distribution over the means of the arms, and at each round samples a mean vector from the distribution and chooses the arm with the highest sampled mean. It then continues to sample mean vectors, until one is returned whose highest mean is different from the previous found one. Both arms are then pulled. As discussed in the introduction, our algorithm is similar in spirit - we sample until finding a parameter vector whose best-arm is different from our current estimate and then we utilize these vectors to update our learners. Top-two algorithms perform well in practice and have been extensively studied in Bayesian and Frequentist settings under various assumptions on noise [11, 25]. We remark that the LinGapE algorithm [33]

also uses a top-two approach and tends to perform well empirically, however it is unknown whether it is asymptotically optimal.

Online Learning and Thompson Sampling Finally we remark that the connection between Thompson Sampling and online learning has been previously explored in the early work of [19]. This work focuses on the regret setting. Recent works in the regret setting have explored connections between information-theoretic analysis of Thompson sampling and online stochastic mirror descent algorithms [16, 35]. We hope that our work provides a first step in this direction for the pure exploration literature.

5 Experiments

In the following, we provide some preliminary experiments to demonstrate the performance of Algorithm 1. Note that the contribution of this paper is primarily theoretical - our goal is to demonstrate that asymptotically optimal algorithms for pure exploration can rely purely on sampling oracles. We hope that the preliminary experiments we provide encourage further exploration of this line of thinking and lead to algorithms that can be as easy to apply as Thompson sampling in practice.

With this in mind, we ran the following modification of some of the algorithms of the previous section. Firstly, we eschewed the doubling trick and instead just ran PEPS directly for a fixed horizon side T . Secondly, for the max-learner we made use of AdaHedge which is able to use an adaptive step size. Finally, we set $\eta_p = 1$. Though our algorithm only has theoretical guarantees over a bounded set Θ , we believe that this is primarily limitation of the analysis and so we set $\Theta = \mathbb{R}^d$. We also remove the forced G -optimal exploration for the same reason. Further details on our experimental setup and additional evaluations are in the Appendix.

The main algorithms we compare to are Thompson Sampling [27] and LinGame [7]. LinGame is based on the two-player game strategy with best-response detailed in Section 2. For a fair comparison, we run LinGame without stopping. The goal of our experiments was to demonstrate that sampling and no-projection algorithms can be competitive against algorithms that explicitly project. From this perspective, we did not consider algorithms that eliminate. For a far more extensive empirical comparison of existing algorithms, please see [31]. We also include an oracle strategy and a comparison to LinGapE [33] in the Appendix.

Soare’s Instance [29]. The first instance we consider is the standard benchmark linear bandit instance described in [29]. In this instance, the arm set $\mathcal{X} \subset \mathbb{R}^2$ with $|\mathcal{X}| = 3$. The first two arms are $x_1 = e_1, x_2 = e_2 \subset \mathbb{R}^2$, the canonical basis vectors, and an informative arm $x_3 = (\cos(\omega), \sin(\omega))$. The true parameter is $\theta_* = (1, 0) \in \mathbb{R}^d$.

In this problem, the optimal arm is always x_1 . However, when the angle ω is small, it becomes challenging to distinguish the interfering arm x_{d+1} from x_1 . An effective sampling strategy would pull arm x_2 instead of x_1 to reduce uncertainty between x_1 and x_{d+1} effectively. However, Thompson sampling will tend to pull x_1 , which will take much longer to distinguish between the two competing arms. The experiments were carried out on a problem instance with $d = 2$ and $\omega = 0.1$. Table 1 presents the average number of pulls for each arm across 100 experimental replications.

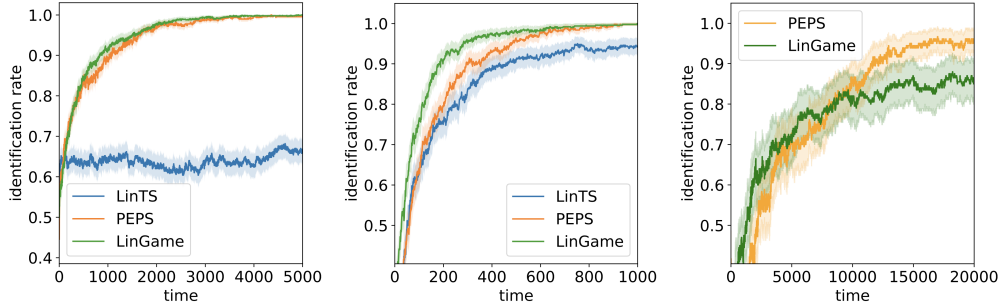


Figure 1: Best-arm identification rate for PEPS, LinGame, and Thompson sampling algorithms under three instances: Soare instance with $\omega = 0.1$, sphere instance with $d = 6$ and $|\mathcal{X}| = 20$, and Top-k instance with $d = 12$ and $k = 3$. We ran 500 repetitions of the Soare and the Sphere instance, and 200 repetitions for Top-K. Confidence intervals with plus or minus two standard errors are shown.

	Soare's instance [29]			Sphere			TopK		
δ	0.1	0.05	0.01	0.1	0.05	0.01	0.2	0.1	0.05
PEPS	1027	1606	3326	294	476	794	8077	11582	15839
LinGame	828	1500	2688	186	282	638	8380	>20000	>20000
LinTS	>5000	>5000	>5000	431	>1000	>1000	N/A	N/A	N/A

Table 1: The number of samples needed for $\mathbb{P}_{\theta \sim \pi_\ell}(\hat{z}_\ell = z_*) > 1 - \delta$ for various algorithms

Sphere. Following [30, 7], we also consider a linear bandit instance where the arm set $\mathcal{X} \subset B^d := \{x \in \mathbb{R}^d : \|x\|_2 = 1\}$ is randomly drawn from a unit sphere of dimension d . For the true parameter, we select the two arms, x and x' , that are closest to each other, and define $\theta_* = x + 0.01(x' - x)$, ensuring that x is the best arm. In our experiment, we run the three algorithms, PEPS, LinGame, and TS, on a problem instance with $d = 6$ and $|\mathcal{X}| = 20$.

As we can see, our algorithm still outperforms Thompson sampling and is competitive with LinGame.

Top-k. The third instance we consider is the top-k combinatorial bandit problem where the goal is to identify the top-k means. In the linear setting, this can be expressed as $\mathcal{X} = \{e_1, \dots, e_d\} \subset \mathbb{R}^d$ and $\mathcal{Z} = \{e_{i_1} + \dots + e_{i_k} : i_1, \dots, i_k \in \binom{[d]}{k}\} \subset \mathbb{R}^d$, i.e. \mathcal{X} is the standard basis and \mathcal{Z} is the set of indicator vectors of subsets of size k . We take $\theta = [1, .95, .90, \dots, 1 - .05i, \dots] \in \mathbb{R}^d$. As we can see, our algorithm outperforms LinGame in this instance.

We also present a table describing the number of samples needed to reach a $1 - \delta$ identification rate for various δ values. Note that we do not run Thompson sampling for the Top-k instance (it is not defined when $\mathcal{X} \neq \mathcal{Z}$ so we put N/A there, and $> n$ in the table means that the algorithm fails to achieve $1 - \delta$ for the n iterations we run in the experiment. We can see that our algorithm, PEPS, achieves an $1 - \delta$ best-arm identification probability for all δ in all instances, with a rate similar to LinGame, outperforming LinTS in all three instances.

6 Conclusion

In this paper, we present the first sampling-based projection-free algorithm for pure exploration in linear bandits. Our algorithm only relies on a sampling oracle and an argmax oracle, so our algorithm is computationally efficient in various settings. We show that our algorithm is asymptotically instance-optimal in the sense that the probability that we do not identify the optimal arm decays exponentially with the optimal rate for a fixed allocation, effectively showing that pure exploration is no harder than Thompson Sampling. We provide some initial experiments demonstrating that our algorithm beats Thompson sampling and has competitive performance against benchmark algorithms such as LinGame [7] in various problem instances. Our current approach has various limitations: for example, we need to assume that Θ is bounded. However, we hope that this work opens a line of investigation into better sampling-based algorithms for effective exploration.

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A Notations and general description

In the following, we let the index t , $1 \leq t \leq T_\ell$ denote the timestep in round ℓ for any ℓ . Throughout this section we will make use of the filtration $\mathcal{F}_t = \{(x_s, \theta_s, y_s)\}_{s=1}^{t-1}$ defined in any round. The table below summarizes the notations used in the proof.

Let $N_{t,x}$ denote the number of times arm x gets pulled at time t . We then define several good

$\bar{p}_{T_\ell} = \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} p_t$	Average of p at the end of round ℓ
$\bar{e}_{T_\ell} = \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} e_{x_t}$	Empirical probability of arms pulled at the end of round ℓ
$\pi_\ell \sim N(\hat{\theta}_{T_\ell+1}, \eta_p^{-1} V_{T_\ell}^{-1})$ restricted on Θ	The distribution θ is sampled from at the end of round ℓ
$\Delta_{\min} = \min_{x \neq x^*} (x^* - x)^\top \theta^*$	minimum gap
$T_2(\ell) = \max_{x \in \mathcal{X}} \left(\frac{6\sqrt{\log(\mathcal{X} T_\ell\ell^2)}}{\lambda_x^G} \right)^4$	a time after which each arm gets sufficiently number of pulls
$T_0(\ell) = \max \left\{ \left(\frac{d\beta(t, \ell^2) \max_{z \in \mathcal{Z}} \ z\ _1}{\Delta_{\min}} \right)^{4/3}, T_2(\ell) + 1 \right\}$	a time after which we have $\hat{z}_t = z_*$ with high probability
$\ell_0 := \min\{\ell : T_\ell \geq T_0(\ell)^{3/2}\}$	minimum round number such that we have guarantee of convergence with high probability
L	upper bound on $\max_{x \in \mathcal{X}} \ x\ _2$
B	upper bound on $\ \theta_*\ _2$
$B_{\mathcal{X}}$	$\max_{x \in \mathcal{X}} \max_{\theta \in \Theta} x^\top \theta$
Δ_{\max}	$\max_{x \in \mathcal{X}} \max_{\theta, \theta' \in \Theta} x^\top (\theta - \theta') $
$\beta(t, 1/\delta) = B + \sqrt{2 \log(1/\delta) + d \log\left(\frac{d+tL^2}{d}\right)}$	anytime confidence bound for $\left\ \hat{\theta}_t - \theta^* \right\ _{V_{t-1}}^2$
$C_{1,\ell} = \Delta_{\max} + L^2 \beta(T_\ell, \ell^2)$	an upper bound on $\max_{x \in \mathcal{X}} \max_{t \leq T_\ell} \langle x, \hat{\theta}_t \rangle $
$C_{3,\ell} = B_{\mathcal{X}} + \Delta_{\max} + L^2 \beta(T_\ell, \ell^2)$	an upper bound on $\max_{x \in \mathcal{X}} \max_{\theta \in \Theta} \max_{t \leq T_\ell} \langle x, \theta - \hat{\theta}_t \rangle $

Table 2: Table of constants and upper bounds used in the proof

events needed to guarantee the performance of PEPS at round ℓ .

$$\begin{aligned}
\mathcal{E}_{1,\ell} &= \bigcup_{t=1}^{T_\ell} \left\{ \left\| \hat{\theta}_t - \theta^* \right\|_{V_{t-1}}^2 \leq \beta(t, \ell^2) \right\}, \\
\mathcal{E}_{2,\ell} &= \bigcup_{t=1}^{T_\ell} \left\{ \max_{x \in \mathcal{X}} |x^\top \hat{\theta}_t| \leq C_{1,\ell} \right\}, \\
\mathcal{E}_{3,\ell} &= \bigcup_{t \geq T_2} \bigcup_{x \in \mathcal{X}} \mathcal{G}_{t,x} \text{ where } \mathcal{G}_{t,x} = \{V_t \geq t^{3/4} A(\lambda^G)\}, \forall t \geq T_2, x \in \mathcal{X} \\
\mathcal{E}_{4,\ell} &= \cup_{t \geq T_0} \mathbf{1}\{\hat{z}_t = z_*\}
\end{aligned}$$

Throughout the proof we also define for some random variable $x \in \mathcal{X}$ with $x \sim p$ and some function $f(x)$,

$$\mathbb{E}_{x \sim p}[f(x)] = \sum_{x \in \mathcal{X}} p_x f(x).$$

The rest of the supplement is organized as follows. In Section B, we present a proof of the lower bound stated in Theorem 2.1. Section F provides more experimental results.

In Section C, we prove the main theorem (Theorem 3.3) stated in the paper by combining a saddle-point convergence argument with a guarantee on the likelihood ratio. We tackle the latter in Section C.1, where we provide we relate the empirical probability of finding the best-arm at the end of a round of PEPS to the likelihood ratio. In Section C.2, we show the saddle point approximation and provide a guarantee on how well τ^* is approximated after one round of PEPS. This argument depends on

- Section C.3 and C.4 which provide regret guarantees on the max and min learners.
- Section C.5 provides lemmas bounding terms related to the approximation error of $\hat{\theta}_{T_\ell}$ to θ^* .
- Section C.6 formally shows that after certain rounds each arm gets enough samples.
- Section D shows that good events needed to guarantee performance of PEPS happen with high probability.

Finally, Section E provides some technical lemmas used in the proof.

B Proof of Theorem 2.1

Theorem B.1. *Fix $\Theta = \mathbb{R}^d$ and any $\theta_* \in \Theta$. For some λ consider a procedure that draws $x_1, \dots, x_T \sim \lambda$, then observes $y_t = \langle x_t, \theta_* \rangle + \epsilon_t$ with $\epsilon_t \sim \mathcal{N}(0, 1)$, and then computes $\hat{z}_T = \arg \max_{z \in \mathcal{Z}} \langle z, \theta_T \rangle$ where $\hat{\theta}_T = \arg \min_{\theta \in \Theta} \sum_{t=1}^T \|y_t - \langle \theta, x_t \rangle\|_2^2$. Then for any $\lambda \in \Delta_{\mathcal{X}}$ we have*

$$\limsup_{T \rightarrow \infty} -\frac{1}{T} \log \left(\mathbb{P}_{\theta_*, x_t \sim \lambda} (\hat{z}_T \neq z_*) \right) \leq \tau^*.$$

Proof. Assume that $\{z - z_*\}_{z \in \mathcal{Z}}$ span \mathbb{R}^d . Otherwise, discard the components of \mathcal{X} and θ_* that are orthogonal to the span of $\{z - z_*\}_{z \in \mathcal{Z}}$ and reparameterize in the subspace spanned by $\{z - z_*\}_{z \in \mathcal{Z}}$. We can then work in this reparameterized space, so without loss of generality we can assume $\{z - z_*\}_{z \in \mathcal{Z}}$ span \mathbb{R}^d .

Furthermore, assume that \mathcal{X} spans \mathbb{R}^d . If this were not true, then there could be a component of θ_* that is orthogonal to the span of \mathcal{X} which makes z_* not identifiable since we assumed $\{z - z_*\}_{z \in \mathcal{Z}}$ spans \mathbb{R}^d . That is, if θ_*^\perp is the projection of θ_* onto the subspace orthogonal to the span of \mathcal{X} , then $\langle z - z_*, \theta_*^\perp \rangle$ could be arbitrarily large but no measurement could detect θ_*^\perp .

Putting the two assumptions together, we conclude that there exists a $\lambda \in \Delta_{\mathcal{X}}$ such that $A(\lambda) \succ 0$ (equivalently, $\lambda_{\min}(A(\lambda)) > 0$) and $\max_{z \in \mathcal{Z}} \|z - z_*\|_{A(\lambda)^{-1}} < \infty$. Fix any λ satisfying such conditions. Define the event $G_\lambda = \{\sum_{t=1}^T x_t x_t^\top \succeq A(\lambda)T(1 - g_{\lambda,T})\}$ for some $g_{\lambda,T} = o(T)$ sequence to be defined next.

By applying matrix Chernoff to the random matrices $\{\frac{1}{T}A(\lambda)^{-1}x_t x_t^\top\}_t$ we have for any $\epsilon \in [0, 1]$ that

$$\mathbb{P}\left(\frac{1}{T} \sum_{t=1}^T x_t x_t^\top \succeq A(\lambda)(1 - \epsilon)\right) \geq 1 - d \exp(-\epsilon^2/2R)$$

where $R = \max_t \lambda_{\max}(\frac{1}{T}A(\lambda)^{-1}x_t x_t^\top)$. Observe that

$$\begin{aligned} \lambda_{\max}\left(\frac{1}{T}A(\lambda)^{-1}x_t x_t^\top\right) &\leq \left\|\frac{1}{T}A(\lambda)^{-1}x_t x_t^\top\right\|_2 \\ &\leq L^2/\lambda_{\min}(A(\lambda))T. \end{aligned}$$

So taking $\epsilon = g_{\lambda,T} = \sqrt{\frac{2L^2 \lambda_{\min}(A(\lambda))^{-1} \log(dT)}{T}}$ we have that $\mathbb{P}(G_\lambda) \geq 1 - 1/T$ whenever $g_{\lambda,T} < 1$ which holds for sufficiently large T .

Now, for any $\{x_t\}_{t=1}^T$ that span \mathbb{R}^d (will be guaranteed by event G_λ) we have that

$$\begin{aligned}\widehat{\theta}_T &= \arg \min_{\theta \in \Theta} \sum_{t=1}^T \|y_t - \langle \theta, x_t \rangle\|_2^2 \\ &= \left(\sum_{t=1}^T x_t x_t^\top \right)^{-1} \sum_{t=1}^T x_t y_t \\ &= \theta_* + \left(\sum_{t=1}^T x_t x_t^\top \right)^{-1} \sum_{t=1}^T x_t \epsilon_t \\ &= \theta_* + \left(\sum_{t=1}^T x_t x_t^\top \right)^{-1/2} \eta\end{aligned}$$

where the last line holds with inequality in distribution for $\eta \sim \mathcal{N}(0, I_d)$. We conclude that for any z that $\langle \widehat{\theta}_T - \theta_*, z - z_* \rangle$ is a zero-mean Gaussian random variable with variance

$$\begin{aligned}\sigma_{z,\lambda}^2 &:= \mathbb{E}[\langle \widehat{\theta}_T - \theta_*, z - z_* \rangle^2] \\ &= \mathbb{E}[\langle \left(\sum_{t=1}^T x_t x_t^\top \right)^{-1/2} \eta, z - z_* \rangle^2] \\ &= (z - z_*)^\top \left(\sum_{t=1}^T x_t x_t^\top \right)^{-1} (z - z_*).\end{aligned}$$

Thus, on G_λ we have that $\sigma_{z,\lambda}^2 \leq \frac{1}{T(1-g_{\lambda,T})} \|z - z_*\|_{A(\lambda)^{-1}}^2$.

Consequently,

$$\begin{aligned}\mathbb{P}_{\theta_*}(\widehat{z}_T \neq z_*) &= \mathbb{P}_{\theta_*} \left(\bigcup_{z \in \mathcal{Z} \setminus z_*} \{\widehat{z}_T = z, z \neq z_*\} \right) \\ &\geq \max_{z \in \mathcal{Z} \setminus z_*} \mathbb{P}_{\theta_*}(\widehat{z}_T = z, z \neq z_*) \\ &= \max_{z \in \mathcal{Z} \setminus z_*} \mathbb{P}_{\theta_*}(\langle \widehat{\theta}_T, z - z_* \rangle \geq 0) \\ &= \max_{z \in \mathcal{Z} \setminus z_*} \mathbb{P}_{\theta_*}(\langle \widehat{\theta}_T - \theta_*, z - z_* \rangle \geq \langle \theta_*, z - z_* \rangle) \\ &\geq \max_{z \in \mathcal{Z} \setminus z_*} \mathbb{E}_{\{x_t\} \sim \lambda} \mathbb{E}_{\theta_*} [\mathbf{1}\{G_\lambda\} \mathbf{1}\{\langle \widehat{\theta}_T - \theta_*, z - z_* \rangle \geq \langle \theta_*, z - z_* \rangle\} | \{x_t\}] \\ &= \max_{z \in \mathcal{Z} \setminus z_*} \mathbb{P}_{\{x_t\} \sim \lambda}(G_\lambda) \mathbb{P}_{\eta_1 \sim \mathcal{N}(0,1)}(\eta_1 \sigma_{z,\lambda} \geq \langle \theta_*, z - z_* \rangle).\end{aligned}$$

Using the fact that

$$\mathbb{P}_{\eta_1 \sim \mathcal{N}(0,1)}(\eta_1 \geq s) = \int_{x=s}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx > \left(\frac{1}{s} - \frac{1}{s^3}\right) \frac{1}{\sqrt{2\pi}} e^{-s^2/2}$$

for positive s , we conclude that

$$\begin{aligned}
& \mathbb{P}_{\theta_*}(\widehat{z}_T \neq z_*) \\
& \geq \max_{z \in \mathcal{Z} \setminus z_*} \mathbb{P}_{\{x_t\} \sim \lambda}(G_\lambda) \mathbb{P}_{\eta_1 \sim \mathcal{N}(0,1)}(\eta_1 \sigma_{z,\lambda} \geq \langle \theta_*, z - z_* \rangle) \\
& \geq \mathbf{1}\{g_{\lambda,T} < 1\} \left(1 - \frac{1}{T}\right) \max_{z \in \mathcal{Z} \setminus z_*} \left(\frac{\sigma_{z,\lambda}}{\langle \theta_*, z - z_* \rangle} - \frac{\sigma_{z,\lambda}^3}{\langle \theta_*, z - z_* \rangle^3} \right) \frac{1}{\sqrt{2\pi}} e^{-\frac{\langle \theta_*, z - z_* \rangle^2}{\sigma_{z,\lambda}^2}} / 2 \\
& \geq \max_{z \in \mathcal{Z} \setminus z_*} \mathbf{1}\{g_{\lambda,T} < 1, \frac{\langle \theta_*, z - z_* \rangle^2}{\sigma_{z,\lambda}^2} \geq 2\} \left(1 - \frac{1}{T}\right) \frac{\sigma_{z,\lambda}}{\langle \theta_*, z - z_* \rangle} \frac{1}{\sqrt{8\pi}} e^{-\frac{\langle \theta_*, z - z_* \rangle^2}{\sigma_{z,\lambda}^2}} / 2 \\
& \geq \max_{z \in \mathcal{Z} \setminus z_*} \mathbf{1}\{g_{\lambda,T} < 1, \frac{T(1-g_{\lambda,T})\langle \theta_*, z - z_* \rangle^2}{\|z - z_*\|_{A(\lambda)}^2} \geq 2\} \left(1 - \frac{1}{T}\right) \frac{\|z - z_*\|_{A(\lambda)}^2}{T(1-g_{\lambda,T})\langle \theta_*, z - z_* \rangle^2} \frac{1}{\sqrt{8\pi}} e^{-\frac{T(1-g_{\lambda,T})\langle \theta_*, z - z_* \rangle^2}{\|z - z_*\|_{A(\lambda)}^2}} / 2.
\end{aligned}$$

Thus, because $g_{\lambda,T} = o(T)$ and $\frac{\|z - z_*\|_{A(\lambda)}^2}{\langle \theta_*, z - z_* \rangle^2} < \infty$ we have that

$$\begin{aligned}
\limsup_{T \rightarrow \infty} -\frac{1}{T} \log \left(\mathbb{P}_{\theta_*, x_t \sim \lambda}(\widehat{z}_T \neq z_*) \right) & \leq \frac{\langle \theta_*, z - z_* \rangle^2}{\|z - z_*\|_{A(\lambda)}^2} / 2 \\
& = \min_{\theta \in \Theta_{z_*}^c} \|\theta - \theta_*\|_{A(\lambda)}^2 / 2 \\
& \leq \max_{\lambda \in \Delta_{\mathcal{X}}} \min_{\theta \in \Theta_{z_*}^c} \|\theta - \theta_*\|_{A(\lambda)}^2 / 2 = \tau^*
\end{aligned}$$

where the second line uses the fact that $\Theta = \mathbb{R}^d$. □

C Proof of the Main Theorem

Theorem C.1. *Under Algorithm 1 and 2 and Assumption 1, we have the sampling distribution satisfies with probability 1,*

$$\lim_{\ell \rightarrow \infty} -\frac{1}{T_\ell} \log \pi_\ell(\Theta_{z_*}^c) = \tau^*.$$

Proof. By Theorem C.2, we have that for $\ell \geq \ell_0$, $\mathbb{P}(\mathcal{E}_\ell^c) \leq \frac{5}{\ell^2}$. Also, since $T_\ell = 2^\ell$, and $T_0(\ell)$ only scales logarithmically in ℓ , so $\ell_0 < \infty$. Therefore, $\sum_{\ell=1}^{\infty} \mathbb{P}(\mathcal{E}_\ell^c) < \infty$. By Borel-Cantelli, we have

$$\mathbb{P} \left(\limsup_{n \rightarrow \infty} \mathcal{E}_\ell^c \right) = 0.$$

Note that $\limsup_{\ell \rightarrow \infty} \mathcal{E}_\ell = \bigcap_{\ell=1}^{\infty} \bigcup_{k=\ell}^{\infty} \mathcal{E}_k$, this implies that the probability that infinitely many of them occur is zero, which means that \mathcal{E}_ℓ eventually holds for sufficiently large ℓ with probability 1.

However, under \mathcal{E}_ℓ we have

$$\begin{aligned}
\pi_\ell(\Theta_{z_*}^c) &= \frac{\int_{\Theta_{z_*}^c} \pi_\ell(\theta) d\theta}{\int_{\Theta} \pi_\ell(\theta) d\theta} = \frac{\int_{\Theta_{z_*}^c} \pi_\ell(\theta)/\pi_\ell(\theta^*) d\theta}{\int_{\Theta} \pi_\ell(\theta)/\pi_\ell(\theta^*) d\theta} \\
&\doteq \frac{\int_{\Theta_{z_*}^c} e^{-\frac{T_\ell}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2} d\theta}{\int_{\Theta} e^{-\frac{T_\ell}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2} d\theta} \quad (\text{by } \mathcal{E}_\ell) \\
&\doteq e^{-T_\ell \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2}. \quad (\text{Lemma E.2 and } \inf_{\theta \in \Theta} \|\theta - \theta^*\|_{A(\lambda)}^2 = 0 \text{ for any } \lambda)
\end{aligned}$$

This implies that there exists some $\epsilon'_\ell \rightarrow 0$ such that

$$\left| -\frac{1}{T_\ell} \log \pi_\ell(\Theta_{z_*}^c) - \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2 \right| \leq \epsilon'_\ell.$$

Under $\mathcal{E}_{6,\ell}$, there exists some sequence $\epsilon_\ell \rightarrow 0$ such that

$$\tau^* - \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2 \leq \epsilon_\ell.$$

Since

$$\tau^* = \max_{\lambda \in \Delta_{\mathcal{X}}} \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\lambda)}^2 \geq \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2,$$

combining the above three displays, we have under \mathcal{E}_ℓ ,

$$\left| -\frac{1}{T_\ell} \log \pi_\ell(\Theta_{z_*}^c) - \tau^* \right| \leq \epsilon_\ell + \epsilon'_\ell,$$

where $\epsilon_\ell + \epsilon'_\ell \rightarrow 0$ as $\ell \rightarrow \infty$. Combining this with the fact that $\mathbb{P}(\limsup_{\ell \rightarrow \infty} \mathcal{E}_\ell) = 0$, we have with probability 1,

$$\lim_{\ell \rightarrow \infty} -\frac{1}{T_\ell} \log \pi_\ell(\Theta_{z_*}^c) = \tau^*.$$

□

Theorem C.2. In round ℓ for $\ell \geq \ell_0$, define

$$\begin{aligned}
\mathcal{E}_{5,\ell} &= \left\{ \sup_{\theta \in \Theta} \frac{1}{T_\ell} \left| \log \frac{\pi_{T_\ell}(\theta^*)}{\pi_{T_\ell}(\theta)} - \frac{T_\ell}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2 \right| \leq \kappa_\ell \right\} \\
\mathcal{E}_{6,\ell} &= \left\{ \left| \max_{\lambda \in \Delta_{\mathcal{X}}} \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\lambda)}^2 - \inf_{\theta \in \Theta_{z_*}^c} \frac{1}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2 \right| \leq \epsilon_\ell \right\}
\end{aligned}$$

with $\epsilon_\ell \rightarrow 0$ and $\kappa_\ell \rightarrow 0$ as $\ell \rightarrow \infty$. Define $\mathcal{E}_\ell = \mathcal{E}_{5,\ell} \cap \mathcal{E}_{6,\ell}$. Then $\mathbb{P}(\mathcal{E}_\ell) \geq 1 - 5/\ell^2$.

Proof. We first summarize the guarantees for the probabilities of events below. For $\ell \geq \ell_0$, we have

- from Lemma C.4, we have that $\mathbb{P}(\mathcal{E}_{6,\ell} | \mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}) \geq 1 - 1/\ell^2$ with choice of $\epsilon_\ell = O(T_\ell^{-1/4})$;

- from Lemma D.1, $\mathbb{P}(\mathcal{E}_{1,\ell}) \geq 1 - 1/\ell^2$;
- by Lemma D.2, $\mathcal{E}_{2,\ell}$ is true under $\mathcal{E}_{3,\ell} \cap \mathcal{E}_{1,\ell}$;
- by Lemma C.16, $\mathbb{P}(\mathcal{E}_{4,\ell}|\mathcal{E}_{1,\ell}) \geq 1 - 1/\ell^2$;
- by Lemma C.3 with $\kappa_\ell = O(T_\ell^{-1/2})$, $\mathbb{P}(\mathcal{E}_{5,\ell}) \geq 1 - 1/\ell^2$;
- by Lemma C.14, $\mathbb{P}(\mathcal{E}_{3,\ell}) \geq 1 - 1/\ell^2$.

Note that $\mathcal{E}_\ell \supset \mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell} \cap \mathcal{E}_{5,\ell} \cap \mathcal{E}_{6,\ell}$, and so

$$\begin{aligned}\mathcal{E}_\ell^c &\subset \mathcal{E}_{1,\ell}^c \cup \mathcal{E}_{2,\ell}^c \cup \mathcal{E}_{3,\ell}^c \cup \mathcal{E}_{4,\ell}^c \cup \mathcal{E}_{5,\ell}^c \cup \mathcal{E}_{6,\ell}^c \\ &= \mathcal{E}_{1,\ell}^c \cup (\mathcal{E}_{2,\ell}^c \cap \mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell}) \cup \mathcal{E}_{3,\ell}^c \cup (\mathcal{E}_{4,\ell}^c \cap \mathcal{E}_{1,\ell}) \cup \mathcal{E}_{5,\ell}^c \cup (\mathcal{E}_{6,\ell}^c \cap \mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}).\end{aligned}$$

Therefore, for $\ell \geq \ell_0$,

$$\begin{aligned}\mathbb{P}(\mathcal{E}_\ell^c) &\leq \mathbb{P}(\mathcal{E}_{1,\ell}^c) + \mathbb{P}(\mathcal{E}_{2,\ell}^c \cap \mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell}) + \mathbb{P}(\mathcal{E}_{3,\ell}^c) + \mathbb{P}(\mathcal{E}_{4,\ell}^c \cap \mathcal{E}_{1,\ell}) + \mathbb{P}(\mathcal{E}_{5,\ell}^c) + \mathbb{P}(\mathcal{E}_{6,\ell}^c \cap \mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}) \\ &\leq \mathbb{P}(\mathcal{E}_{1,\ell}^c) + \mathbb{P}(\mathcal{E}_{2,\ell}^c|\mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell})\mathbb{P}(\mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell}) + \mathbb{P}(\mathcal{E}_{3,\ell}^c) + \mathbb{P}(\mathcal{E}_{4,\ell}^c|\mathcal{E}_{1,\ell})\mathbb{P}(\mathcal{E}_{1,\ell}) \\ &\quad + \mathbb{P}(\mathcal{E}_{5,\ell}^c) + \mathbb{P}(\mathcal{E}_{6,\ell}^c|\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell})\mathbb{P}(\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}) \\ &\leq \mathbb{P}(\mathcal{E}_{1,\ell}^c) + \mathbb{P}(\mathcal{E}_{2,\ell}^c|\mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell}) + \mathbb{P}(\mathcal{E}_{3,\ell}^c) + \mathbb{P}(\mathcal{E}_{4,\ell}^c|\mathcal{E}_{1,\ell}) + \mathbb{P}(\mathcal{E}_{5,\ell}^c) + \mathbb{P}(\mathcal{E}_{6,\ell}^c|\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}) \\ &\leq \frac{5}{\ell^2}.\end{aligned}$$

Therefore, $\mathbb{P}(\mathcal{E}_\ell) \geq 1 - \frac{5}{\ell^2}$. □

C.1 Guarantees on the Likelihood Ratio

Lemma C.3. *We have with probability at least $1 - 1/\ell^2$,*

$$\sup_{\theta \in \Theta} \frac{1}{T_\ell} \left| \log \frac{\pi_\ell(\theta)}{\pi_\ell(\theta^*)} - \frac{T_\ell}{2} \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2 \right| \leq \Delta_{\max} \sqrt{\frac{2d \log \left(\frac{(d+T_\ell L^2)\ell^2}{d} \right)}{T_\ell}}.$$

Which implies that $\frac{\pi_\ell(\theta)}{\pi_\ell(\theta^*)} \doteq e^{-T_\ell \|\theta - \theta^*\|_{A(\bar{e}_{T_\ell})}^2}$.

Proof. Throughout the following we set $T := T_\ell$. Recall that $\pi_\ell(\theta) = \mathcal{N}(\hat{\theta}_{T+1}, V_T^{-1})$ restricted on Θ , which means that for each $\theta \in \Theta$,

$$\pi_\ell(\theta) = \frac{\exp \left(-\frac{1}{2} \left\| \theta - \hat{\theta}_{T+1} \right\|_{V_T}^2 \right)}{\int_{\Theta} \exp \left(-\frac{1}{2} \left\| \theta' - \hat{\theta}_{T+1} \right\|_{V_T}^2 \right) d\theta'}.$$

Since the denominator is independent of θ , this means that

$$\frac{\pi_\ell(\theta)}{\pi_\ell(\theta^*)} = \exp \left(-\frac{1}{2} \left(\left\| \theta - \hat{\theta}_{T+1} \right\|_{V_T}^2 - \left\| \theta^* - \hat{\theta}_{T+1} \right\|_{V_T}^2 \right) \right)$$

where

$$\begin{aligned}
& \left\| \theta^* - \hat{\theta}_{T+1} \right\|_{V_T}^2 - \left\| \theta - \hat{\theta}_{T+1} \right\|_{V_T}^2 \\
&= \left\| \theta^* \right\|_{V_T}^2 - 2(\theta^*)^\top V_T \hat{\theta} + \left\| \hat{\theta}_{T+1} \right\|_{V_T}^2 - \left\| \hat{\theta}_{T+1} \right\|_{V_T}^2 + 2(\hat{\theta}_{T+1})^\top V_T \theta - \left\| \theta \right\|_{V_T}^2 \\
&= \left\| \theta^* \right\|_{V_T}^2 - 2(\theta^*)^\top V_T \left(\theta^* + V_T^{-1} \sum_{s=1}^T \epsilon_s x_s \right) + 2\theta^\top V_T \left(\theta^* + V_T^{-1} \sum_{s=1}^T \epsilon_s x_s \right) - \left\| \theta \right\|_{V_T}^2 \\
&= \left\| \theta^* \right\|_{V_T}^2 - 2 \left\| \theta^* \right\|_{V_T}^2 - 2(\theta^*)^\top \left(\sum_{s=1}^T \epsilon_s x_s \right) + 2(\theta^*)^\top V_T \theta + 2\theta^\top \left(\sum_{s=1}^T \epsilon_s x_s \right) - \left\| \theta \right\|_{V_T}^2 \\
&= -\left\| \theta^* - \theta \right\|_{V_T}^2 - 2 \left\langle \theta^* - \theta, \sum_{s=1}^T \epsilon_s x_s \right\rangle \\
&= -\left\| \theta^* - \theta \right\|_{V_T}^2 - 2 \sum_{s=1}^T \epsilon_s x_s^\top (\theta^* - \theta).
\end{aligned}$$

Note that

$$\begin{aligned}
\sum_{s=1}^T \epsilon_s x_s^\top (\theta^* - \theta) &= \sum_{s=1}^T \epsilon_s x_s^\top V_T^{-1/2} V_T^{1/2} (\theta^* - \theta) \\
&\leq \left\| \sum_{s=1}^T \epsilon_s x_s \right\|_{V_T^{-1}} \left\| \theta^* - \theta \right\|_{V_T}.
\end{aligned}$$

Note that

$$\left\| \theta^* - \theta \right\|_{V_T} = \sqrt{\left\| \theta^* - \theta \right\|_{V_T}^2} = \sqrt{\sum_{t=1}^T (x_t^\top (\theta^* - \theta))^2} \leq \Delta_{\max} \sqrt{T},$$

and since $\mathbb{E}[\epsilon_s x_s | \mathcal{F}_{s-1}] = 0$ for all s , $\epsilon_s x_s$ is a vector-valued martingale. Then by Theorem 1 of [1], with probability greater than $1 - \delta$,

$$\left\| \sum_{s=1}^T \epsilon_s x_s \right\|_{V_T^{-1}} \leq \sqrt{2d \log \left(\frac{d + TL^2}{d\delta} \right)}$$

so with probability $1 - \delta$,

$$\left\| \sum_{s=1}^T \epsilon_s x_s \right\|_{V_T^{-1}} \left\| \theta^* - \theta \right\|_{V_T} \leq \Delta_{\max} \sqrt{T} \sqrt{2d \log \left(\frac{d + TL^2}{d\delta} \right)}.$$

so for any $\theta \in \Theta$,

$$\left| \left(\left\| \theta - \hat{\theta}_{T+1} \right\|_{V_T}^2 - \left\| \theta^* - \hat{\theta}_{T+1} \right\|_{V_T}^2 \right) - \left\| \theta^* - \theta \right\|_{V_T}^2 \right| \leq \Delta_{\max} \sqrt{T} \sqrt{2d \log \left(\frac{d + TL^2}{d\delta} \right)},$$

which means that

$$\left| \log \frac{\pi_\ell(\theta^*)}{\pi_\ell(\theta)} - \frac{T}{2} \|\theta - \theta^*\|_{A(\bar{e}_T)}^2 \right| \leq \Delta_{\max} \sqrt{T} \sqrt{2d \log \left(\frac{d + TL^2}{d\delta} \right)}.$$

Taking a supremum over $\theta \in \Theta$ on both sides and taking $\delta = \frac{1}{\ell^2}$ gives the result. \square

C.2 Guarantee on Saddle-Point Convergence of PEPS in Round ℓ

In this section, we present a key result to this proof, which shows that as round ℓ gets large, the distribution from PEPS achieves the optimal allocation deduced by τ^* . Fix a round ℓ . At iteration t , let $\tilde{\lambda}_t$ denote the sampling distribution of x_t . The result is stated in the following lemma. In the proof, we decompose the difference into several terms and argue about each piece in subsequent sections.

Lemma C.4 (Guarantee for PEPS). *On $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}$, for $\ell > \ell_0$ then at the end of epoch ℓ , we have with probability at least $1 - \frac{1}{\ell^2}$,*

$$\tau^* - \inf_{\theta \in \Theta_{z_*}^c} \left[\frac{1}{2} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right] \leq \epsilon_\ell$$

for a sequence $\epsilon_\ell \rightarrow 0$ as $\ell \rightarrow \infty$.

Proof. Recall the definition of \bar{p}_{T_ℓ} and \bar{e}_{T_ℓ} in Section A. We first show that there exists some ϵ_ℓ that goes to zero as $\ell \rightarrow \infty$ such that under $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{3,\ell} \cap \mathcal{E}_{4,\ell}$, for $\ell > \ell_0$,

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{F}_{\theta \sim \bar{p}_{T_\ell}} \left[\frac{1}{2} \|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} \left[\frac{1}{2} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right] \leq \epsilon_\ell.$$

We have

$$\begin{aligned}
& \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{E}_{\theta \sim p} \left[\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right] \\
&= \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \\
&= \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 + C_{T_\ell}'' \\
&= \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\lambda)}^2 \right] \tag{S1. } C_{T_\ell}' \\
&+ \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\lambda)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \tag{S2. regret for max learner}
\end{aligned}$$

$$+ \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \tag{S3.}$$

$$+ \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] \tag{S4.}$$

$$+ \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \tag{S5. regret for the min learner}$$

$$+ C_{T_\ell}'',$$

where we define

$$\begin{aligned}
C_{T_\ell}' &:= \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\lambda)}^2 \right] \\
C_{T_\ell}'' &= \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 - \inf_{\theta \in \Theta_{z_*}^c} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2.
\end{aligned}$$

We now handle each term separately by referring to the lemma which provides a guarantee.

- **(S1)** By Lemma C.10, under $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$, for $T_\ell \geq T_2(\ell)$,

$$\begin{aligned}
& \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \hat{\theta}_t - \theta \right\|_{A(\lambda)}^2 \right] \\
&\leq \frac{T_2(\ell)L^2\beta(T_2(\ell), \ell^2)}{T_\ell} + 4d\beta(T_\ell, \ell^2)T_\ell^{-3/4},
\end{aligned}$$

so for $T_\ell \geq T_2(\ell)^{3/2}$, we have the above is upper bounded by

$$O(L^2\beta(T_2(\ell), \ell^2)T_\ell^{-1/2} + 4d\beta(T_\ell, \ell^2)T_\ell^{-3/4});$$

- (S2) By Lemma C.5, we have with probability $1 - 1/(3\ell^2)$ conditioned on $\mathcal{E}_{2,\ell}$

$$\begin{aligned} & \max_{\lambda \in \Delta_{\mathcal{X}}} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \tilde{\lambda}_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ & \leq 2C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell |\mathcal{X}| \log(T_\ell \ell^2)} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t, \end{aligned}$$

so with a choice of $\gamma_t = t^{-\alpha}$ with $\alpha = 1/4$,

$$\begin{aligned} & \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \tilde{\lambda}_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ & \leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell}^{-1/2} + \sqrt{2C_{3,\ell}^2 \log \ell^2 T_\ell}^{-1/2} + \sqrt{2C_{3,\ell}^2 |\mathcal{X}| \log(3T_\ell \ell^2) T_\ell}^{-1/2} + 2C_{3,\ell}^2 T_\ell^{-1/4} \end{aligned}$$

- (S3) By Lemma C.12, we have conditioned on $\mathcal{E}_{4,\ell} \cap \mathcal{E}_{1,\ell}$ for $\ell \geq \ell_0$,

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \leq \frac{2C_{3,\ell}^2 T_0(\ell)}{T_\ell}$$

for $T_\ell \geq T_0(\ell)^{3/2}$, we have the above is bounded by $2C_{3,\ell}^2 T_\ell^{-1/2}$;

- (S4) By Lemma C.8, we have with probability $1 - 1/(3\ell^2)$, conditioned on $\mathcal{E}_{2,\ell}$,

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] \leq \sqrt{\frac{2C_{1,\ell} \log \ell^2}{T_\ell}}$$

- (S5) By Lemma C.7, we have with probability $1 - 1/(3\ell^2)$, conditioned on $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$,

$$\begin{aligned} & \frac{1}{T_\ell} \left[\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right] \\ & \leq \sqrt{\frac{C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})}{T_\ell}} + C_{3,\ell} \sqrt{\frac{2d\beta(T_\ell, \ell^2)}{T_\ell} \log \left(\frac{d + T_\ell L^2}{d} \right)} + C_{3,\ell} \sqrt{\frac{2 \log(\ell^2)}{T_\ell}}. \end{aligned}$$

- (C''_{T_ℓ}) By Lemma C.11, conditioned on $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$, we have

$$\left| \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 - \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta^* - \theta \right\|_{V_{T_\ell}}^2 \right| \leq (C_{3,\ell} + \Delta_{\max}) \sqrt{\frac{\beta(T_\ell, \ell^2)}{T_\ell}}$$

Add them altogether, we get that with probability greater than $1 - 1/\ell^2$ on $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell} \cap \mathcal{E}_{4,\ell}$

$$\begin{aligned}
& \max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{E}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{E}_{\theta \sim p} \left[\|\theta^* - \theta\|_{A(\bar{\lambda}_{T_\ell})}^2 \right] \\
& \leq L^2 \beta(T_2(\ell), \ell^2) T_\ell^{-1/2} + 4d\beta(T_\ell, \ell^2) T_\ell^{-3/4} \\
& \quad + C_{3,\ell}^2 \sqrt{\log |\mathcal{X}|} T_\ell^{-1/2} + \sqrt{2C_{3,\ell}^2 \log \ell^2 T_\ell^{-1/2}} + \sqrt{2C_{3,\ell}^2 |\mathcal{X}| \log(3T\ell^2) T_\ell^{-1/2}} + C_{3,\ell}^2 T_\ell^{-1/4} \\
& \quad + 2C_{3,\ell}^2 T_\ell^{-1/2} + \sqrt{\frac{2C_{1,\ell} \log \ell^2}{T_\ell}} \\
& \quad + \sqrt{\frac{C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})}{T_\ell}} + C_{3,\ell} \sqrt{\frac{2d\beta(T_\ell, \ell^2)}{T_\ell} \log \left(\frac{d + T_\ell L^2}{d} \right)} + C_{3,\ell} \sqrt{\frac{2 \log(\ell^2)}{T_\ell}} \\
& \quad + (C_{3,\ell} + \Delta_{\max}) \sqrt{\frac{\beta(T_\ell, \ell^2)}{T_\ell}}.
\end{aligned}$$

Note that each term approaches zero as $T_\ell \rightarrow \infty$. By the choice of $T_\ell = 2^\ell$ in the algorithm, this implies that there exists some $\epsilon_\ell > 0$ with $\epsilon_\ell \rightarrow 0$ as $\ell \rightarrow \infty$ such that for each ℓ ,

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{F}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} \left[\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right] \leq \epsilon_\ell. \quad (2)$$

Now we show how this result leads to the saddle point convergence. Note that

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \mathbb{F}_{\theta \sim \bar{p}_{T_\ell}} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] \geq \max_{\lambda \in \Delta_{\mathcal{X}}} \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} [\|\theta^* - \theta\|_{A(\lambda)}^2] \geq \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} \left[\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right],$$

so using Equation 2 we have

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} [\|\theta^* - \theta\|_{A(\lambda)}^2] - \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} \left[\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right] \leq \epsilon_\ell.$$

However, note that

$$\min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} \left[\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right] = \inf_{\theta \in \Theta_{z_*}^c} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2$$

and $\max_{\lambda \in \Delta_{\mathcal{X}}} \min_{p \in \mathcal{P}(\Theta_{z_*}^c)} \mathbb{F}_{\theta \sim p} [\|\theta^* - \theta\|_{A(\lambda)}^2] = \tau^*$, we have shown that

$$\tau^* - \inf_{\theta \in \Theta_{z_*}^c} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 < \epsilon_\ell.$$

□

C.3 Guarantees on the max-learner

In this section, we show that the max-learner gets sublinear regret as ℓ gets large. The key idea is that we mix a diminishing amount of G -optimal distribution each round, and we show that by its diminishing nature, the mixing of G -optimal distribution keeps the regret sublinear.

Lemma C.5. Under $\mathcal{E}_{\ell,2}$, with the choice of $\eta_\lambda = \sqrt{\frac{\log |\mathcal{X}|}{C_{3,\ell}^4 T}}$, we have with probability greater than $1 - 1/\ell^2$,

$$\begin{aligned} & \max_{\lambda \in \Delta_{\mathcal{X}}} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \tilde{\lambda}_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ & \leq 2C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell |\mathcal{X}| \log(T_\ell \ell^2)} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t. \end{aligned}$$

Proof. We first show that the statement is true for some fixed λ , i.e. we would like to show that with probability $1 - \delta$,

$$\begin{aligned} & \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \tilde{\lambda}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\ & \leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell \log(1/\delta)} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t. \end{aligned}$$

Let \mathcal{F}_{t-1} be the history up to time t . Then for any fixed λ ,

$$\mathbb{E}_{\theta_t} [\mathbb{F}_{x \sim \lambda} [\left\| \hat{\theta}_t - \theta_t \right\|_{xx^\top}^2] | \mathcal{F}_{t-1}] = \mathbb{F}_{\theta \sim p_t, x \sim \lambda} [\left\| \hat{\theta}_t - \theta \right\|_{xx^\top}^2].$$

Thus, setting

$$\begin{aligned} X_t &= \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \mathbb{F}_{x \sim \tilde{\lambda}_t, \theta \sim p_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ &\quad - \left[\mathbb{F}_{x \sim \lambda} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \mathbb{F}_{x \sim \lambda, \theta \sim p_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \end{aligned}$$

we see that the X_t form a Martingale difference sequence, i.e. $\mathbb{E}[X_t | \mathcal{F}_{t-1}] = 0$. Note that for any $\theta \in \Theta$,

$$\begin{aligned} & \mathbb{F}_{x \sim \lambda_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\ &= \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] + \gamma_t \left(\mathbb{F}_{x \sim \lambda_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \mathbb{F}_{x \sim \lambda_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \right), \end{aligned}$$

Since under $\mathcal{E}_{2,\ell}$, we have for any $x \in \mathcal{X}$, $\theta \in \Theta$, any $t \leq T_\ell$, $\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \leq C_{3,\ell}^2$, we have for any $\theta \in \Theta$,

$$\mathbb{F}_{x \sim \lambda_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \leq \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] + 2C_{3,\ell}^2 \gamma_t.$$

Then we have

$$\begin{aligned}
& \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \tilde{\lambda}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\
&= \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \lambda} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\
&\quad - \left[\sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \lambda} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \right] \\
&\quad - \left[\sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t, \theta \sim p_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\
&\leq \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \lambda} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\
&\quad - \left[\sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \lambda} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \right] \\
&\quad - \left[\sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t, \theta \sim p_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t \tag{3}
\end{aligned}$$

Note that

$$\begin{aligned}
& \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \lambda} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t} \left[\left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\
&\quad - \left[\sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{F}_{x \sim \tilde{\lambda}_t, \theta \sim p_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] = \sum_{t=1}^{T_\ell} X_t.
\end{aligned}$$

We know that under $\mathcal{E}_{2,\ell}$, we have for any $x \in \mathcal{X}$, $\theta \in \Theta$, any $t \leq T_\ell$, $\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \leq C_{3,\ell}^2$. Then, for any t , $|X_t| \leq 4C_{3,\ell}^2$, so by Azuma-Hoeffding, with probability $1 - \delta$, $\sum_{t=1}^{T_\ell} X_t \leq \sqrt{8C_{3,\ell}^2 T_\ell \log(1/\delta)}$. Plugging the above and Lemma C.6 in Equation 3 gives us

$$\begin{aligned}
& \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] - \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t, x \sim \tilde{\lambda}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \right] \\
&\leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell \log(1/\delta)} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t.
\end{aligned}$$

This result holds for any λ , but in particular we want it to hold for the λ which maximizes the reward, so we perform a covering argument on λ .

We take an ϵ -cover \mathcal{S}_ϵ of $\Delta_{\mathcal{X}}$ in $\|\cdot\|_1$. Then, we know that for any $\lambda \in \Delta_{\mathcal{X}}$, there is some $\lambda' \in \mathcal{S}_\epsilon$ such that $\|\lambda - \lambda'\|_1 \leq \epsilon$. Let $w_t(\lambda) := \mathbb{F}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2$. Then, note that for any t and

$$\lambda_1, \lambda_2 \in \Delta_{\mathcal{X}},$$

$$\begin{aligned} w(\lambda_1) - w(\lambda_2) &= \mathbb{E}_{\theta \sim p_t, x \sim \lambda_1} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \mathbb{E}_{\theta \sim p_t, x \sim \lambda_2} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ &= \mathbb{E}_{\theta \sim p_t} \sum_x ([\lambda_1]_x - [\lambda_2]_x) (x^\top (\theta - \hat{\theta}_t))^2 \\ &\leq C_{3,\ell}^2 \mathbb{E}_{\theta \sim p_t} \sum_x ([\lambda_1]_x - [\lambda_2]_x) \\ &= C_{3,\ell}^2 \|\lambda_1 - \lambda_2\|_1, \end{aligned}$$

so $w_t(\lambda)$ is $C_{3,\ell}^2$ -Lipschitz for any t . Then, assuming that $\bar{\lambda} \in \Delta_{\mathcal{X}}$ satisfies that

$$\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \bar{\lambda}} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 = \max_{\lambda \in \Delta_{\mathcal{X}}} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2,$$

we can find some $\lambda_0 \in \mathcal{S}_\epsilon$ such that $\|\lambda_0 - \bar{\lambda}\| \leq \epsilon$, so by Lipschitzness of w_t for any t , we have

$$\begin{aligned} &\max_{\lambda \in \Delta_{\mathcal{X}}} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \max_{\lambda \in \mathcal{S}_\epsilon} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ &= \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \bar{\lambda}} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \max_{\lambda \in \mathcal{S}_\epsilon} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ &\leq \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \bar{\lambda}} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda_0} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ &\leq C_{3,\ell}^2 T_\ell \epsilon. \end{aligned}$$

Also, let $K = |\mathcal{X}|$. Denote B_1^K as the l_1 ball with dimension K . We know that for $\epsilon \leq 1$, $N(B_1^K, \|\cdot\|_1, \epsilon) \leq \left(\frac{3}{\epsilon}\right)^K$. Since $\Delta_{\mathcal{X}} \subset B_1^K$, we have the covering number

$$N(\Delta_{\mathcal{X}}, \|\cdot\|_1, \epsilon) \leq N(B_1^K, \|\cdot\|_1, \epsilon) \leq \left(\frac{3}{\epsilon}\right)^K.$$

Therefore, $|\mathcal{S}_\epsilon| \leq \left(\frac{3}{\epsilon}\right)^K$. By union bounding over all $\lambda \in \mathcal{S}_\epsilon$, we have with probability at least $1 - \delta$,

$$\begin{aligned} &\max_{\lambda \in \mathcal{S}_\epsilon} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ &\leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell \log(1/(\delta |\mathcal{S}_\epsilon|))} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t \\ &\leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell |\mathcal{X}| \log(3/(\epsilon \delta))} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t. \end{aligned}$$

Combining two displays gives us

$$\begin{aligned} & \max_{\lambda \in \Delta_{\mathcal{X}}} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 - \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t, x \sim \lambda_t} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \\ & \leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell} + \sqrt{2C_{3,\ell}^2 T_\ell |\mathcal{X}| \log(3/(\delta\epsilon))} + 2C_{3,\ell}^2 \sum_{t=1}^{T_\ell} \gamma_t + C_{3,\ell}^2 T_\ell \epsilon. \end{aligned}$$

Taking $\epsilon = 1/\sqrt{T_\ell}$ and $\delta = 1/\ell^2$ gives us the result. \square

Lemma C.6. Under $\mathcal{E}_{2,\ell}$, with the choice of $\eta = \sqrt{\frac{\log |\mathcal{X}|}{C_{3,\ell}^4 T_\ell}}$, we have for any λ ,

$$\sum_{t=1}^{T_\ell} \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda)}^2 - \sum_{t=1}^{T_\ell} \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda_t)}^2 \leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell}.$$

Proof. Let $\ell_t(\lambda) = - \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda)}^2$. Then we have

$$[\nabla_\lambda \ell_t(\lambda_t)]_x = - \left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 = \tilde{g}_{t,x}.$$

Since

$$\max_{t \in [T_\ell]} \|\tilde{g}_t\|_\infty = \max_{t \in [T_\ell], x \in \mathcal{X}} \left\| \theta_t - \hat{\theta}_t \right\|_{xx^\top}^2 \leq C_{3,\ell}^2,$$

by the guarantee of exponentiated gradient algorithm [24], we have that for any λ ,

$$\sum_{t=1}^{T_\ell} [\ell_t(\lambda_t) - \ell_t(\lambda)] \leq \frac{\log |\mathcal{X}|}{\eta} + \frac{\eta T_\ell}{2} C_{3,\ell}^4.$$

Plugging in the definition of $\ell_t(\lambda)$, we have

$$\sum_{t=1}^{T_\ell} \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda)}^2 - \sum_{t=1}^{T_\ell} \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda_t)}^2 \leq \frac{\log |\mathcal{X}|}{\eta} + \frac{\eta T_\ell}{2} C_{3,\ell}^4.$$

Choosing $\eta = \sqrt{\frac{\log |\mathcal{X}|}{C_{3,\ell}^4 T_\ell}}$, we have

$$\sum_{t=1}^{T_\ell} \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda)}^2 - \sum_{t=1}^{T_\ell} \left\| \theta_t - \hat{\theta}_t \right\|_{A(\lambda_t)}^2 \leq C_{3,\ell}^2 \sqrt{\log |\mathcal{X}| T_\ell}.$$

\square

C.4 Guarantees on the min-learner

In this section, we show that the min-learner gets sublinear regret as ℓ gets large. For the min learner, we see that the update for the sampling distribution is very similar to the continuous exponential weights updates [3]. The difference between our setting and continuous exponential weights is that the space $\Theta_{z_t}^c$ is changing each time, so we potentially have a changing action space each time. To overcome this challenge, we first analyze the regret guarantee when we assume access to the true alternative in Lemma C.7, and use Lemma C.16 to argue that the estimate $\Theta_{z_t}^c$ is good enough. We state the following guarantee for the min-learner.

Lemma C.7. *On event $\mathcal{E}_{\ell,1} \cap \mathcal{E}_{\ell,2}$, with probability $1 - 1/\ell^2$,*

$$\begin{aligned} & \frac{1}{T_\ell} \left[\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right] \\ & \leq \sqrt{\frac{C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})}{T_\ell}} + C_{3,\ell} \sqrt{\frac{2d\beta(T_\ell, \ell^2)}{T_\ell} \log\left(\frac{d + T_\ell L^2}{d}\right)} + C_{3,\ell} \sqrt{\frac{2 \log(\ell^2)}{T_\ell}}. \end{aligned}$$

Proof. We begin by a bound that will be useful in our exponential weights analogy. At iteration t , we apply Hoeffding's lemma with the following upper bound given $\mathcal{E}_{\ell,1} \cap \mathcal{E}_{\ell,2}$ and Lemma E.1,

$$\begin{aligned} & \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] \\ & \leq C_{3,\ell}^2 + \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_{t+1} \right\|_{V_{t-1}}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2 \right] \quad (\mathcal{E}_{\ell,2}) \\ & \leq C_{3,\ell}^2 + 2C_{3,\ell}(C_{1,\ell} + 1) \quad (\text{Lemma E.1}) \\ & \leq 4C_{3,\ell}^2. \end{aligned}$$

At round $t > 1$, we define $W_t = \int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2\right) d\theta$ and W_1 being a uniform distribution on $\Theta_{z_*}^c$. Then

$$\begin{aligned} & \log \frac{W_{t+1}}{W_t} \\ & = \log \frac{\int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2\right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2\right) d\theta} \\ & = \log \frac{\int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \eta_p \left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \eta_p \left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2 - \eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2\right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2\right) d\theta} \\ & = \log \frac{\int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 - \eta_p \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 + \eta_p \left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 - \eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2\right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} \exp\left(-\eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2\right) d\theta} \\ & \leq -\eta_p \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] + \frac{\eta_p^2 \cdot 4C_{3,\ell}^2}{8} \end{aligned}$$

where the inequality follows from the Hoeffding inequality $\ln \mathbb{E} e^{sX} \leq s\mathbb{E}X + \frac{s^2(a-b)^2}{8}$. By telescoping, we have

$$\begin{aligned} \log \frac{W_{T_\ell+1}}{W_1} &= \ln \frac{W_{T_\ell+1}}{W_{T_\ell}} + \ln \frac{W_{T_\ell}}{W_{T_\ell-1}} + \cdots + \ln \frac{W_2}{W_1} \\ &\leq -\eta_p \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] + \frac{T_\ell \eta_p^2 C_{3,\ell}^2}{2}. \end{aligned}$$

On the other hand, let $\tilde{\theta} = \arg \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2$. Let $w_t(\theta) = \exp \left(-\eta_p \left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2 \right)$. Let

$\mathcal{N}_\gamma := \{(1-\gamma)\tilde{\theta} + \gamma\theta, \theta \in \Theta_{z_*}^c\}$ for $\gamma > 0$ that we choose later. We have

$$\begin{aligned}
\log \frac{W_{T_\ell+1}}{W_1} &= \log \left(\frac{\int_{\theta \in \Theta_{z_*}^c} \exp \left(-\eta_p \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&\geq \log \left(\frac{\int_{\theta \in \mathcal{N}_\gamma} \exp \left(-\eta_p \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&\geq \log \left(\frac{\int_{\theta \in \gamma \Theta_{z_*}^c} \exp \left(-\eta_p \left\| (1-\gamma)\tilde{\theta} + \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&= \log \left(\frac{\int_{\theta \in \Theta_{z_*}^c} \gamma^d \exp \left(-\eta_p \left\| (1-\gamma)\tilde{\theta} + \gamma\theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&= \log \left(\frac{\int_{\theta \in \Theta_{z_*}^c} \gamma^d \exp \left(-\eta_p \left\| (1-\gamma)\tilde{\theta} + \gamma\theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&\geq \log \left(\frac{\int_{\theta \in \Theta_{z_*}^c} \gamma^d \exp \left(-\eta_p \left((1-\gamma) \left\| \tilde{\theta} - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 + \gamma \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&\geq \log \left(\frac{\int_{\theta \in \Theta_{z_*}^c} \gamma^d \exp \left(-\eta_p \left((1-\gamma) \left\| \tilde{\theta} - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 + \gamma \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right) \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&\geq \log \left(\frac{\int_{\theta \in \Theta_{z_*}^c} \gamma^d \exp \left(-\eta_p \left(\left\| \tilde{\theta} - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 + \gamma T_\ell C_{1,\ell} \right) \right) d\theta}{\int_{\theta \in \Theta_{z_*}^c} 1 d\theta} \right) \\
&= -\eta_p \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 + d \log \gamma - \eta_p \gamma T_\ell C_{1,\ell}.
\end{aligned}$$

where the last inequality follows from the fact that for any $\theta \in \Theta$,

$$\left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 = \sum_{t=1}^{T_\ell} (x_t^\top (\theta - \hat{\theta}_{T_\ell+1}))^2 \leq T_\ell C_{3,\ell}^2$$

under $\mathcal{E}_{2,\ell}$. Combining the two displays gives us

$$\begin{aligned} & -\eta_p \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 + d \log \gamma - \eta_p \gamma T_\ell C_{1,\ell} \\ & \leq -\eta_p \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] + \frac{T_\ell \eta_p^2 C_{3,\ell}^2}{2}. \end{aligned}$$

Rearranging, we have

$$\begin{aligned} & \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \\ & \leq \frac{\eta_p C_{3,\ell}^2 T_\ell}{2} + \frac{d \log(1/\gamma)}{\eta_p} + \gamma T_\ell C_{1,\ell}. \end{aligned}$$

By choosing $\gamma = \frac{1}{T_\ell C_{1,\ell}}$ and $\eta_p = \sqrt{\frac{d \log(T_\ell C_{1,\ell})}{C_{3,\ell}^2 T_\ell}}$, we have

$$\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \leq \sqrt{T_\ell C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})},$$

so

$$\frac{1}{T_\ell} \left[\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t(\Theta_{z_*}^c)} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 + \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right] \leq \sqrt{\frac{C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})}{T_\ell}}.$$

In other words,

$$\begin{aligned} & \frac{1}{T_\ell} \left[\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right] \\ & \leq \sqrt{\frac{C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})}{T_\ell}} + \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right]. \end{aligned}$$

By Lemma C.9, we have with probability $1 - 1/\ell^2$,

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] \leq C_{3,\ell} \sqrt{\frac{2d\beta(T_\ell, \ell^2)}{T_\ell} \log \left(\frac{d + T_\ell L^2}{d} \right)} + C_{3,\ell} \sqrt{\frac{2 \log(\ell^2)}{T_\ell}}.$$

Combining the above two displays gives us with probability $1 - 1/\ell^2$,

$$\begin{aligned} & \frac{1}{T_\ell} \left[\sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 \right] \\ & \leq \sqrt{\frac{C_{3,\ell}^2 d \log(T_\ell C_{1,\ell})}{T_\ell}} + C_{3,\ell} \sqrt{\frac{2d\beta(T_\ell, \ell^2)}{T_\ell} \log \left(\frac{d + T_\ell L^2}{d} \right)} + C_{3,\ell} \sqrt{\frac{2 \log(\ell^2)}{T_\ell}}. \end{aligned}$$

□

C.5 Approximation Guarantees

In this section, we present several technical lemmas bounding the terms related to the approximation error of $\hat{\theta}_t$ to θ^* in each iteration t . More specifically, these lemmas show upper bound on the terms in the decomposition in the proof of lemma C.4.

Lemma C.8 (S4). *Under $\mathcal{E}_{2,\ell}$, with probability $1 - 1/\ell^2$,*

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] \leq \sqrt{\frac{2C_{1,\ell} \log \ell^2}{T_\ell}}.$$

Proof. Define $M_t = \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right]$. Note that

$$\mathbb{E}_{x_t} [M_t | \mathcal{F}_{t-1}] = \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right],$$

so $\tilde{M}_t = M_t - \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right]$ is a mean-zero martingale. Also, under $\mathcal{E}_{2,\ell}$, $|M_t| \leq C_{1,\ell}$, then by Azuma-Hoeffding, we have with probability at least $1 - \frac{1}{\ell^2}$, $\sum_{t=1}^{T_\ell} \tilde{M}_t \leq \sqrt{2C_{1,\ell} T_\ell \log \ell^2}$, so

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{x_t x_t^\top}^2 \right] \leq \sqrt{\frac{2C_{1,\ell} \log \ell^2}{T_\ell}}.$$

□

Lemma C.9 (C_{T_ℓ}). *Under $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$, with probability $1 - 1/\ell^2$,*

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \right] \leq C_{3,\ell} \sqrt{\frac{2d\beta(T_\ell, \ell^2)}{T_\ell} \log \left(\frac{d + T_\ell L^2}{d} \right)} + C_{3,\ell} \sqrt{\frac{2 \log(\ell^2)}{T_\ell}}.$$

Proof. We first consider some round t and some θ . By Lemma E.1,

$$\left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2 - \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_{t-1}}^2 \leq 2C_{3,\ell} (y_t - x_t^\top \hat{\theta}_t).$$

Therefore,

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{V_{t-1}}^2 - \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_{t-1}}^2 \right] \leq \frac{2C_{3,\ell}}{T_\ell} \sum_{t=1}^{T_\ell} (y_t - x_t^\top \hat{\theta}_t). \quad (4)$$

Now, note that

$$\begin{aligned} y_t - x_t^\top \hat{\theta}_t &= x_t^\top (\theta^* - \hat{\theta}_t) + \epsilon_t \\ &\leq \|x_t\|_{V_{t-1}^{-1}} \left\| \theta^* - \hat{\theta}_t \right\|_{V_{t-1}} + \epsilon_t \\ &\leq \|x_t\|_{V_{t-1}^{-1}} \sqrt{\beta(t, \ell^2)} + \epsilon_t. \end{aligned} \quad (\text{by } \mathcal{E}_{1,\ell})$$

Note that since $\epsilon_t \sim N(0,1)$ is 1-subGaussian, by Azuma-Hoeffding, we have with probability $1 - 1/\ell^2$,

$$\sum_{t=1}^{T_\ell} \epsilon_t \leq \sqrt{2T_\ell \log(\ell^2)}.$$

By summing it from 1 to T_ℓ , we have under $\mathcal{E}_{1,\ell}$, with probability $1 - 1/\ell^2$,

$$\begin{aligned} \sum_{t=1}^{T_\ell} (y_t - x_t^\top \hat{\theta}_t) &\leq \sum_{t=1}^{T_\ell} \sqrt{\beta(t, \ell^2)} \|x_t\|_{V_{t-1}^{-1}} + \sum_{t=1}^{T_\ell} \epsilon_t \\ &\leq \sum_{t=1}^{T_\ell} \sqrt{\beta(t, \ell^2)} \|x_t\|_{V_{t-1}^{-1}} + \sqrt{2T_\ell \log(\ell^2)} \\ &\leq \sqrt{T_\ell \sum_{t=1}^{T_\ell} \beta(t, \ell^2) \|x_t\|_{V_{t-1}^{-1}}^2} + \sqrt{2T_\ell \log(\ell^2)} \quad (\text{by Cauchy-Schwarz}) \\ &\leq \sqrt{T_\ell \beta(T_\ell, \ell^2) \sum_{t=1}^{T_\ell} \|x_t\|_{V_{t-1}^{-1}}^2} + \sqrt{2T_\ell \log(\ell^2)} \quad (\text{by Cauchy-Schwarz}) \\ &\leq \sqrt{T_\ell \beta(T_\ell, \ell^2) 2d \log\left(\frac{d + T_\ell L^2}{d}\right)} + \sqrt{2T_\ell \log(\ell^2)}. \end{aligned}$$

(by Elliptical potential lemma [1])

Plugging this in Equation 4 gives the result. \square

Lemma C.10 (C'_{T_ℓ}). *Under $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$, we have*

$$\begin{aligned} &\max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\hat{\theta}_t - \theta\|_{A(\lambda)}^2 \right] \\ &\leq \frac{T_2(\ell) L^2 \beta(T_2(\ell), \ell^2)}{T_\ell} + 4d\beta(T_\ell, \ell^2) T_\ell^{-3/4}. \end{aligned}$$

Proof. We have

$$\begin{aligned} &\max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 \right] - \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\hat{\theta}_t - \theta\|_{A(\lambda)}^2 \right] \\ &\leq \max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 - \|\hat{\theta}_t - \theta\|_{A(\lambda)}^2 \right]. \end{aligned}$$

We fix some θ and λ . Note that

$$\begin{aligned}
& \|\theta^* - \theta\|_{A(\lambda)}^2 - \|\hat{\theta}_t - \theta\|_{A(\lambda)}^2 \\
&= (\theta^* + \hat{\theta}_t - 2\theta)^\top A(\lambda) (\theta^* - \hat{\theta}_t) \\
&= \sum_{x \in \mathcal{X}} \lambda_x (\theta^* + \hat{\theta}_t - 2\theta)^\top x x^\top (\theta^* - \hat{\theta}_t) \\
&\leq \max_{x \in \mathcal{X}} (\theta^* + \hat{\theta}_t - 2\theta)^\top x x^\top (\theta^* - \hat{\theta}_t) \\
&\leq (C_{3,\ell} + \Delta_{\max}) \max_{x \in \mathcal{X}} x^\top (\theta^* - \hat{\theta}_t).
\end{aligned}$$

Therefore,

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 - \|\hat{\theta}_t - \theta\|_{A(\lambda)}^2 \right] \leq (C_{3,\ell} + \Delta_{\max}) \max_{x \in \mathcal{X}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \langle \hat{\theta}_t - \theta^*, x \rangle. \quad (5)$$

By Lemma C.15, under $\mathcal{E}_{3,\ell} \cap \mathcal{E}_{1,\ell}$, for any $t \geq T_2(\ell) + 1$, we have for any $x \in \mathcal{X}$,

$$\langle x, \hat{\theta}_t - \theta^* \rangle \leq \frac{d}{t^{3/4}} \beta(t, \ell^2).$$

Also, by Lemma D.2, under $\mathcal{E}_{1,\ell}$, we have for any $t \geq 1$,

$$\langle x, \hat{\theta}_t - \theta^* \rangle \leq L^2 \beta(t, \ell^2).$$

Therefore,

$$\begin{aligned}
& \max_{x \in \mathcal{X}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \langle \hat{\theta}_t - \theta^*, x \rangle \\
&\leq \max_{x \in \mathcal{X}} \frac{1}{T_\ell} \left[\sum_{t=1}^{T_2(\ell)} \langle \hat{\theta}_t - \theta^*, x \rangle + \sum_{t=T_2(\ell)+1}^{T_\ell} \langle \hat{\theta}_t - \theta^*, x \rangle \right] \\
&\leq \frac{1}{T_\ell} \left[T_2(\ell) L^2 \beta(T_2(\ell), \ell^2) + \sum_{t=T_2(\ell)+1}^{T_\ell} \frac{d}{t^{3/4}} \beta(t, \ell^2) \right] \quad (\text{by Lemma D.2 and C.15}) \\
&\leq \frac{1}{T_\ell} \left[T_2(\ell) L^2 \beta(T_2(\ell), \ell^2) + d \beta(T_\ell, \ell^2) \int_{t=T_2(\ell)}^{T_\ell} t^{-3/4} dt \right] \\
&= \frac{1}{T_\ell} \left[T_2(\ell) L^2 \beta(T_2(\ell), \ell^2) + d \beta(T_\ell, \ell^2) (4T_\ell^{1/4} - 4T_2(\ell)^{1/4}) \right] \\
&\leq \frac{T_2(\ell) L^2 \beta(T_2(\ell), \ell^2)}{T_\ell} + 4d \beta(T_\ell, \ell^2) T_\ell^{-3/4}.
\end{aligned}$$

Plugging this in Equation 5 gives us

$$\max_{\lambda \in \Delta_{\mathcal{X}}} \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{F}_{\theta \sim p_t} \left[\|\theta^* - \theta\|_{A(\lambda)}^2 - \|\hat{\theta}_t - \theta\|_{A(\lambda)}^2 \right] \leq \frac{T_2(\ell) L^2 \beta(T_2(\ell), \ell^2)}{T_\ell} + 4d \beta(T_\ell, \ell^2) T_\ell^{-3/4}.$$

□

Lemma C.11 (C''_{T_ℓ}). Assume that Θ is closed. Then, we have under $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$,

$$\left| \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 - \frac{1}{T_\ell} \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta^* - \theta \right\|_{V_{T_\ell}}^2 \right| \leq (C_{3,\ell} + \Delta_{\max}) \sqrt{\frac{\beta(T_\ell, \ell^2)}{T_\ell}}.$$

Proof. Let $\theta_1 := \arg \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2$ and $\theta_2 := \arg \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \theta^* \right\|_{V_{T_\ell}}^2$. We have

$$\begin{aligned} & \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta^* - \theta \right\|_{V_{T_\ell}}^2 \\ & \leq \left\| \hat{\theta}_{T_\ell+1} - \theta_2 \right\|_{V_{T_\ell}}^2 - \left\| \theta^* - \theta_2 \right\|_{V_{T_\ell}}^2 \\ & = \left(\left\| \hat{\theta}_{T_\ell+1} - \theta_2 \right\|_{V_{T_\ell}} - \left\| \theta^* - \theta_2 \right\|_{V_{T_\ell}} \right) \left(\left\| \hat{\theta}_{T_\ell+1} - \theta_2 \right\|_{V_{T_\ell}} + \left\| \theta^* - \theta_2 \right\|_{V_{T_\ell}} \right) \\ & \leq \left\| \hat{\theta}_{T_\ell+1} - \theta^* \right\|_{V_{T_\ell}} \left(\left\| \hat{\theta}_{T_\ell+1} - \theta_2 \right\|_{V_{T_\ell}} + \left\| \theta^* - \theta_2 \right\|_{V_{T_\ell}} \right). \end{aligned}$$

Note that under $\mathcal{E}_{2,\ell}$,

$$\begin{aligned} \left\| \hat{\theta}_{T_\ell+1} - \theta_1 \right\|_{V_{T_\ell}} &= \sqrt{\sum_{t=1}^{T_\ell} (x_t^\top (\hat{\theta}_{T_\ell+1} - \theta_1))^2} \leq C_{3,\ell} \sqrt{T_\ell}; \\ \left\| \theta^* - \theta_2 \right\|_{V_{T_\ell}} &= \sqrt{\sum_{t=1}^{T_\ell} (x_t^\top (\theta^* - \theta_2))^2} \leq \Delta_{\max} \sqrt{T_\ell}. \end{aligned}$$

Therefore,

$$\begin{aligned} & \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta - \hat{\theta}_{T_\ell+1} \right\|_{V_{T_\ell}}^2 - \inf_{\theta \in \Theta_{z_*}^c} \left\| \theta^* - \theta \right\|_{V_{T_\ell}}^2 \\ & \leq (C_{3,\ell} + \Delta_{\max}) \sqrt{T_\ell} \left\| \hat{\theta}_{T_\ell+1} - \theta^* \right\|_{V_{T_\ell}} \\ & \leq (C_{3,\ell} + \Delta_{\max}) \sqrt{T_\ell \beta(T_\ell, \ell^2)}. \end{aligned} \tag{by $\mathcal{E}_{1,\ell}$ }$$

□

We use the above lemma to bound the term that relates \tilde{p}_t to p_t .

Lemma C.12 (\tilde{p}_t to p_t). Under $\mathcal{E}_{2,\ell} \cap \mathcal{E}_{4,\ell}$ for $T_\ell \geq T_0$,

$$\frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \leq \frac{2C_{3,\ell}^2 T_0(\ell)}{T_\ell}.$$

Proof. Note that $\tilde{p}_t = p_t$ under $\mathcal{E}_{4,\ell}$,

$$\begin{aligned}
& \frac{1}{T_\ell} \sum_{t=1}^{T_\ell} \left(\mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \right) \\
&= \frac{1}{T_\ell} \sum_{t=1}^{T_0(\ell)} \left(\mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \right) \\
&\quad + \frac{1}{T_\ell} \sum_{t=T_0(\ell)+1}^{T_\ell} \left(\mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \right) \\
&= \frac{1}{T_\ell} \sum_{t=1}^{T_0(\ell)} \left(\mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \right).
\end{aligned}$$

Since for any $\theta \in \Theta$, under $\mathcal{E}_{2,\ell}$,

$$\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 = \sum_{x \in \mathcal{X}} \tilde{\lambda}_{t,x} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \leq \max_{x \in \mathcal{X}} \left\| \theta - \hat{\theta}_t \right\|_{xx^\top}^2 \leq C_{3,\ell}^2,$$

we have

$$\frac{1}{T_\ell} \sum_{t=1}^{T_0(\ell)} \left(\mathbb{E}_{\theta \sim p_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] - \mathbb{E}_{\theta \sim \tilde{p}_t} \left[\left\| \theta - \hat{\theta}_t \right\|_{A(\tilde{\lambda}_t)}^2 \right] \right) \leq \frac{2C_{3,\ell}^2 T_0(\ell)}{T_\ell}.$$

□

C.6 Guarantees on sampling and learning the estimate

In this section we provide some general guarantees on sampling together with a threshold after which each arm gets enough samples and . Consider a setting where at each time we receive a distribution $\tilde{\lambda} = (1 - \gamma_t)\lambda_t + \gamma_t P$ for a fixed distribution P .

Lemma C.13. *Fix a distribution P on \mathcal{X} with full support. On an event that is true with probability greater than $1 - \delta$, for any $0 < \alpha < 1/2$ there exists a $T_1 := T_1(\alpha, \delta, T)$ such that for any $t \geq T_1$,*

$$V_t \geq \frac{c}{1 - \alpha} A(P) t^{1-\alpha}.$$

Proof. Fix $x \in \mathcal{X}$, let $N_{t,x} = \sum_{s=1}^t Z_s$ where $Z_s = 1$ if $x_s = x$ else 0. Then, $V_t = \sum_{x \in \mathcal{X}} \sum_{s=1}^t Z_s x x^\top$. We assume that $\gamma_s = 1/s^\alpha$, $s \geq 1$.

Note that $\mathbb{P}(Z_s = 1 | \mathcal{F}_{s-1}) = (1 - \gamma_s)\lambda_{s,x} + \gamma_s P_x$. So for $t > 1$,

$$\begin{aligned}
\mathbb{P}\left(\sum_{s=1}^t Z_s \leq cP_x \sum_{s=1}^t \gamma_s\right) &= \mathbb{P}\left(\sum_{s=1}^t Z_s - (1 - \gamma_s)\lambda_{s,x} - \gamma_s P_x \leq \sum_{s=1}^t cP_x \gamma_s - (1 - \gamma_s)\lambda_{s,x} - \gamma_s P_x\right) \\
&= \mathbb{P}\left(\sum_{s=1}^t Z_s - (1 - \gamma_s)\lambda_{s,x} - \gamma_s P_x \leq \sum_{s=1}^t (c - 1)P_x \gamma_s - (1 - \gamma_s)\lambda_{s,x}\right) \\
&\leq \mathbb{P}\left(\sum_{s=1}^t Z_s - (1 - \gamma_s)\lambda_{s,x} - \gamma_s P_x \leq \sum_{s=1}^t (c - 1)P_x \gamma_s\right) \\
&\leq \mathbb{P}\left(\sum_{s=1}^t Z_s - (1 - \gamma_s)\lambda_{s,x} - \gamma_s P_x \leq -\sum_{s=1}^t (1 - c)P_x \gamma_s\right) \\
&\leq \exp\left(-\frac{1}{t} \left(\sum_{s=1}^t (1 - c)P_x \gamma_s\right)^2\right) \quad (\text{Azuma-Hoeffding}) \\
&= \exp\left(-\left(\frac{(1 - c)P_x}{\sqrt{t}} \sum_{s=1}^t \gamma_s\right)^2\right) \\
&\leq \exp\left(-\left(\frac{(1 - c)P_x}{\sqrt{t}} \frac{t^{1-\alpha} - 1}{1 - \alpha}\right)^2\right) \quad (\sum_{s=1}^t \frac{1}{s^\alpha} \geq \frac{t^{1-\alpha} - 1}{1 - \alpha}) \\
&\leq \exp\left(-\left((1 - c)P_x \frac{t^{1/2-\alpha} - t^{-1/2}}{1 - \alpha}\right)^2\right) \\
&\leq \exp\left(-\left(\frac{(1 - c)P_x}{2(1 - \alpha)} t^{1/2-\alpha}\right)^2\right) \quad (t^{1/2-\alpha} - t^{-1/2} > \frac{1}{2}t^{1/2-\alpha}, t \geq 2) \\
&\leq \exp\left(-\left(\frac{(1 - c)P_x}{2(1 - \alpha)}\right)^2 t^{1-2\alpha}\right)
\end{aligned}$$

This implies that with the sequence $\gamma_s = 1/s^\alpha, \alpha < 1/2$ (to ensure $1 - 2\alpha > 0$), with probability greater than $1 - \delta$ we have

$$N_{t,x} = \sum_{s=1}^t Z_s \geq cP_x \sum_{s=1}^t \gamma_s \geq \frac{cP_x}{1 - \alpha} (t^{1-\alpha} - 1) \quad \text{whenever} \quad t \geq \left(\frac{2(1 - \alpha)\sqrt{\log(1/\delta)}}{(1 - c)P_x}\right)^{\frac{2}{1-2\alpha}}.$$

□

The lemma below states that there exists some time T_2 such that all the arms get enough samples.

Lemma C.14. For $T_2(\ell) = \max_{x \in \mathcal{X}} \left(\frac{6\sqrt{\log(|\mathcal{X}|T_\ell \ell^2)}}{\lambda_x^G}\right)^4$, we have

$$\mathbb{P}(\mathcal{E}_{3,\ell}) \geq 1 - 1/\ell^2.$$

Proof. By Lemma C.13 with a choice of $c = 1 - \alpha$, $\alpha = \frac{1}{4}$, $\delta = \frac{1}{|\mathcal{X}|T_\ell\ell^2}$, and $P = \lambda^G$, we have for any $t \geq \left(\frac{2(1-\alpha)\sqrt{\log(1/\delta)}}{(1-c)P_x}\right)^{\frac{2}{1-2\alpha}} = \left(\frac{6\sqrt{\log(|\mathcal{X}|T_\ell\ell^2)}}{\lambda_x^G}\right)^4$, we have $\mathbb{P}(V_t \geq t^{3/4}A(\lambda^G)) \geq 1 - \frac{1}{|\mathcal{X}|T_\ell\ell^2}$. Let $T_2(\ell) := \max_{x \in \mathcal{X}} \left(\frac{6\sqrt{\log(|\mathcal{X}|T_\ell\ell^2)}}{\lambda_x^G}\right)^4$, union bounding for $t \in [T_2, T_\ell]$ and $x \in \mathcal{X}$ gives the result. \square

Lemma C.15. *Under $\mathcal{E}_{3,\ell} \cap \mathcal{E}_{1,\ell}$, for any $t \geq T_2(\ell) + 1$, we have for any $x \in \mathcal{X}$,*

$$\langle x, \hat{\theta}_t - \theta^* \rangle \leq \frac{d}{t^{3/4}} \beta(t, \ell^2).$$

Proof. Let $N_{t,x}$ be the number of times arm x gets pulled at round t . By Lemma C.14, for $t \geq T_2(\ell) + 1$, under $\mathcal{E}_{3,\ell}$, we have

$$V_{t-1} = \sum_{x \in \mathcal{X}} N_{t-1,x} x x^\top \geq t^{3/4} A(\lambda^G).$$

Therefore, for any $x \in \mathcal{X}$,

$$\|x\|_{V_{t-1}^{-1}}^2 \leq \frac{1}{t^{3/4}} \|x\|_{A(\lambda^G)^{-1}}^2 \leq \frac{d}{t^{3/4}}$$

by Kiefer-Wolfowitz. Therefore, under $\mathcal{E}_{1,\ell}$, for any $x \in \mathcal{X}$,

$$\begin{aligned} \langle x, \hat{\theta}_t - \theta^* \rangle &\leq \|x\|_{V_{t-1}^{-1}}^2 \left\| \hat{\theta}_t - \theta^* \right\|_{V_{t-1}}^2 \\ &\leq \frac{d}{t^{3/4}} \left\| \hat{\theta}_t - \theta^* \right\|_{V_{t-1}}^2 \\ &\leq \frac{d}{t^{3/4}} \beta(t, \ell^2). \end{aligned}$$

\square

The following lemma provides a guarantee that we eventually finds z_* .

Lemma C.16. *For $T_0(\ell) = \max \left\{ \left(\frac{d\beta(T_\ell, \ell^2) \max_{z \in \mathcal{Z}} \|z\|_1}{\Delta_{\min}} \right)^{4/3}, T_2(\ell) + 1 \right\}$, we have $\mathbb{P}(\mathcal{E}_{4,\ell} | \mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell}) \geq 1 - 1/\ell^2$.*

Proof. By Lemma C.15, we know that for any $t \geq T_2(\ell) + 1$, under $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{3,\ell}$ we have for any $x \in \mathcal{X}$,

$$\langle x, \hat{\theta}_t - \theta^* \rangle \leq \frac{d}{t^{3/4}} \beta(t, \ell^2).$$

Since the span of \mathcal{Z} is in the subset of \mathcal{X} , for any $z \in \mathcal{Z}$, we write $z_* - z = \sum_{x \in \mathcal{X}} \alpha_{z,x} x$. Then

$$\begin{aligned} (z_* - z)^\top (\theta_* - \hat{\theta}_t) &= \sum_{x \in \mathcal{X}} \alpha_{z,x} x^\top (\theta_* - \hat{\theta}_t) \\ &\leq \sum_{x \in \mathcal{X}} \alpha_{z,x} \frac{d}{t^{3/4}} \beta(t, \ell^2) \\ &\leq \max_{z \in \mathcal{Z}} \|z\|_1 \frac{d}{t^{3/4}} \beta(t, \ell^2). \end{aligned}$$

Then, for any $t > \left(\frac{d\beta(t, \ell^2) \max_{z \in \mathcal{Z}} \|z\|_1}{\Delta_{\min}} \right)^{4/3}$, we have

$$\max_{z \in \mathcal{Z}} \|z\|_1 \frac{d}{t^{3/4}} \beta(t, \ell^2) < \Delta_{\min},$$

which implies that for any z ,

$$\begin{aligned} (z_* - z)^\top (\theta_* - \hat{\theta}_t) &< \Delta_{\min} \\ \Rightarrow (z_* - z)^\top (\hat{\theta}_t - \theta_*) &> -\Delta_{\min} \\ \Rightarrow (z_* - z)^\top \hat{\theta}_t &> 0, \end{aligned}$$

which implies that $\hat{z}_t = z_*$. □

D Bounds and Events that Hold True Each Round

The following lemma states an anytime confidence bound for the least-squares estimator. It is a restatement of Theorem 20.5 of [18] in our setting.

Lemma D.1 ($\mathcal{E}_{1,\ell}$). *With probability $1 - 1/\ell^2$, for all t , we have*

$$\left\| \hat{\theta}_t - \theta^* \right\|_{V_{t-1}}^2 \leq B + \sqrt{2 \log(\ell^2) + d \log \left(\frac{d + tL^2}{d} \right)}.$$

Proof. Follows from Theorem 20.5 of [18]. □

Lemma D.2 ($\mathcal{E}_{2,\ell}$). *Under $\mathcal{E}_{1,\ell}$, we have for any $x \in \mathcal{X}$ and any $t \in [1, T_\ell]$, $\langle x, \hat{\theta}_t \rangle \leq \Delta_{\max} + L^2 \beta(T_\ell, \ell^2)$.*

Proof. For any $x \in \mathcal{X}$,

$$\begin{aligned} \langle x, \hat{\theta}_t \rangle &= \langle x, \theta^* \rangle + \langle x, \hat{\theta}_t - \theta^* \rangle \\ &\leq \Delta_{\max} + \|x\|_{V_{t-1}^{-1}}^2 \left\| \hat{\theta}_t - \theta^* \right\|_{V_{t-1}}^2 \\ &\leq \Delta_{\max} + \|x\|_{V_{t-1}^{-1}}^2 \beta(t, \ell^2). \end{aligned} \quad (\text{under } \mathcal{E}_{1,\ell})$$

Since we have

$$V_{t-1} = V_0 + \sum_{s=1}^{t-1} x_s x_s^\top,$$

for $V_0 = I$, we have the minimum eigenvalue $\sigma_{\min}(V_{t-1}) \geq \sigma_{\min}(V_0) + \sigma_{\min} \left(\sum_{s=1}^{t-1} x_s x_s^\top \right) \geq 1$, so

$$\sigma_{\max}(V_{t-1}^{-1}) = \frac{1}{\sigma_{\min}(V_{t-1})} \leq 1,$$

which implies that

$$\max_{x \in \mathcal{X}} \|x\|_{V_{t-1}^{-1}}^2 \leq \sigma_{\max}(V_{t-1}^{-1}) \max_{x \in \mathcal{X}} \|x\|_2^2 \leq L^2.$$

Therefore,

$$\langle x, \hat{\theta}_t \rangle \leq \Delta_{\max} + L^2 \beta(t, \ell^2) \leq \Delta_{\max} + L^2 \beta(T_\ell, \ell^2).$$

□

E Technical Lemmas

Lemma E.1 (Recursive Least Squares Guarantee). *In any round ℓ , conditional on event $\mathcal{E}_{1,\ell} \cap \mathcal{E}_{2,\ell}$, for any $\theta \in \Theta$ and any $t \in [1, T_\ell]$ we have*

$$\left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \leq 2C_{3,\ell}(y_t - x_t^\top \hat{\theta}_t) \leq 2C_{3,\ell}(C_{1,\ell} + 1),$$

assuming that all rewards are bounded in $[-1, 1]$.

Proof. We first consider some round t and some θ . Note that $\hat{\theta}_t = V_t^{-1} X_t^\top Y_t$. Then

$$\begin{aligned} \hat{\theta}_{t+1} &= (V_{t-1} + x_t x_t^\top)^{-1} (X_{t-1}^\top Y_{t-1} + x_t y_t) \\ &= \left(V_{t-1}^{-1} - \frac{V_{t-1}^{-1} x_t x_t^\top V_{t-1}^{-1}}{1 + x_t^\top V_{t-1}^{-1} x_t} \right) (X_{t-1}^\top Y_{t-1} + x_t y_t) \\ &= \hat{\theta}_t - \frac{V_{t-1}^{-1} x_t x_t^\top \hat{\theta}_t}{1 + x_t^\top V_{t-1}^{-1} x_t} + V_{t-1}^{-1} x_t y_t - \frac{V_{t-1}^{-1} x_t x_t^\top V_{t-1}^{-1} x_t y_t}{1 + x_t^\top V_{t-1}^{-1} x_t} \\ &= \hat{\theta}_t - \frac{V_{t-1}^{-1} x_t x_t^\top \hat{\theta}_t}{1 + x_t^\top V_{t-1}^{-1} x_t} + \frac{V_{t-1}^{-1} x_t y_t (1 + x_t^\top V_{t-1}^{-1} x_t) - x_t^\top V_{t-1}^{-1} x_t V_{t-1}^{-1} x_t y_t}{(1 + x_t^\top V_{t-1}^{-1} x_t)} \\ &= \hat{\theta}_t - \frac{V_{t-1}^{-1} x_t x_t^\top \hat{\theta}_t}{1 + x_t^\top V_{t-1}^{-1} x_t} + \frac{V_{t-1}^{-1} x_t y_t}{(1 + x_t^\top V_{t-1}^{-1} x_t)} \\ &= \hat{\theta}_t + \frac{V_{t-1}^{-1} x_t (y_t - x_t^\top \hat{\theta}_t)}{1 + x_t^\top V_{t-1}^{-1} x_t} \end{aligned}$$

Hence

$$\hat{\theta}_{t+1} - \hat{\theta}_t = \frac{V_{t-1}^{-1} x_t}{1 + x_t^\top V_{t-1}^{-1} x_t} (y_t - x_t^\top \hat{\theta}_t)$$

and

$$\begin{aligned} V_t(\hat{\theta}_{t+1} - \hat{\theta}_t) &= \frac{V_t V_{t-1}^{-1} x_t}{1 + x_t^\top V_{t-1}^{-1} x_t} (y_t - x_t^\top \hat{\theta}_t) \\ &= \frac{(I + x_t x_t^\top V_{t-1}^{-1}) x_t}{1 + x_t^\top V_{t-1}^{-1} x_t} (y_t - x_t^\top \hat{\theta}_t) \\ &= \frac{x_t (1 + x_t^\top V_{t-1}^{-1} x_t)}{1 + x_t^\top V_{t-1}^{-1} x_t} (y_t - x_t^\top \hat{\theta}_t) \\ &= (y_t - x_t^\top \hat{\theta}_t) x_t \end{aligned}$$

Then

$$\begin{aligned}
& \left\| \theta - \hat{\theta}_{t+1} \right\|_{V_t}^2 - \left\| \theta - \hat{\theta}_t \right\|_{V_t}^2 \\
&= (\hat{\theta}_{t+1} - \hat{\theta}_t)^\top V_t (\hat{\theta}_{t+1} + \hat{\theta}_t - 2\theta) \\
&= (y_t - x_t^\top \hat{\theta}_t) x_t^\top (\hat{\theta}_{t+1} + \hat{\theta}_t - 2\theta) \\
&\leq 2C_{3,\ell} (y_t - x_t^\top \hat{\theta}_t) \\
&\leq 2C_{3,\ell} (C_{1,\ell} + 1)
\end{aligned}$$

assuming all rewards are bounded by 1. \square

Lemma E.2. *For any open set $\tilde{\Theta} \subset \Theta$, we have*

$$\int_{\tilde{\Theta}} \exp \left(-\frac{T_\ell}{2} \left(\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right) \right) d\theta = \exp \left(-\frac{T_\ell}{2} \inf_{\theta \in \tilde{\Theta}} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right).$$

Proof. The following argument is inspired by an analogous one in Lemma 11 of [26]. Let $\iota_\ell := \int_{\tilde{\Theta}} \exp \left(-\frac{T_\ell}{2} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right) d\theta$ and $W_{T_\ell}(\theta) := \frac{1}{2} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2$. Also, let $\tilde{\theta}_\ell \in \text{closure}(\tilde{\Theta})$ be a point that attains the infimum, i.e.

$$\tilde{\theta}_\ell := \arg \inf_{\theta \in \tilde{\Theta}} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2.$$

Such a point must exist by the continuity of $W_{T_\ell}(\theta)$ and $\text{closure}(\tilde{\Theta})$ being compact. Then, we first observe that

$$\int_{\tilde{\Theta}} \exp \left(-\frac{T_\ell}{2} \|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 \right) d\theta \leq \text{Vol}(\tilde{\Theta}) \exp \left(-\frac{T_\ell}{2} \|\theta^* - \tilde{\theta}_\ell\|_{A(\bar{e}_{T_\ell})}^2 \right),$$

so

$$\limsup_{\ell \rightarrow \infty} \frac{1}{T_\ell} \log(\iota_\ell) + W_{T_\ell}(\tilde{\theta}_\ell) \leq 0.$$

Second, we fix some arbitrary $\epsilon > 0$. Note that for any $\theta, \theta' \in \Theta$,

$$\begin{aligned}
|W_{T_\ell}(\theta) - W_{T_\ell}(\theta')| &= \frac{1}{2} \left(\|\theta^* - \theta\|_{A(\bar{e}_{T_\ell})}^2 - \|\theta^* - \theta'\|_{A(\bar{e}_{T_\ell})}^2 \right) \\
&= \frac{1}{2} ((2\theta^* - \theta - \theta')^\top A(\bar{e}_{T_\ell})(\theta - \theta')) \\
&= \frac{1}{2T_\ell} \sum_{t=1}^{T_\ell} ((2\theta^* - \theta - \theta')^\top x_t x_t^\top (\theta - \theta')) \\
&\leq \Delta_{\max} \max_{x \in \mathcal{X}} x^\top (\theta - \theta') \\
&\leq \Delta_{\max} \max_{x \in \mathcal{X}} \|x\|_2 \|\theta - \theta'\|_2 \\
&\leq L \Delta_{\max} \|\theta - \theta'\|_2.
\end{aligned}$$

Then, there exists $\delta > 0$ such that

$$\|\theta - \theta'\|_2 < \delta \Rightarrow |W_{T_\ell}(\theta) - W_{T_\ell}(\theta')| < \epsilon.$$

Then, we take a δ -cover of Θ with $\|\cdot\|_2$, and intersect them with $\tilde{\Theta}$, and denote the resulting cover as \mathcal{O} . Then, $\tilde{\theta}_\ell \in O$ for some $O \in \mathcal{O}$. Since we know that $\text{Vol}(O) > 0$ for any $O \in \mathcal{O}$, we have

$$\iota_\ell \geq \int_O \exp(-T_\ell W_{T_\ell}(\theta)) d\theta \geq \text{Vol}(O) \exp\left(-T_\ell \left(W_{T_\ell}(\tilde{\theta}_\ell) - \epsilon\right)\right).$$

Taking logarithm on both sides implies that

$$\frac{1}{T_\ell} \log(\iota_\ell) + W_{T_\ell}(\tilde{\theta}_\ell) \geq \frac{\text{Vol}(O)}{T_\ell} - \epsilon \rightarrow -\epsilon.$$

Since we choose $\epsilon > 0$ arbitrarily, we have

$$\liminf_{\ell \rightarrow \infty} \frac{1}{T_\ell} \log(\iota_\ell) + W_{T_\ell}(\tilde{\theta}_\ell) \geq 0.$$

Therefore, $\lim_{\ell \rightarrow \infty} \frac{1}{T_\ell} \log(\iota_\ell) + W_{T_\ell}(\tilde{\theta}_\ell) = 0$ and the statement follows. \square

F Supplementary plots

In this section, we present more supplementary plots. We run each instance for 500 repetitions and compare the following algorithms: Thompson sampling, PEPS, LinGame [7], LinGapE [33], and the fixed weights strategy where arms are pulled from the optimal allocation λ^* obtained from τ^* . We plot identification rates and arm pull probabilities for the above algorithms. Figure 2 presents the identification rates for different algorithms respectively. Table 3 presents the number of samples needed to reach a $1 - \delta$ identification rate for various δ values.

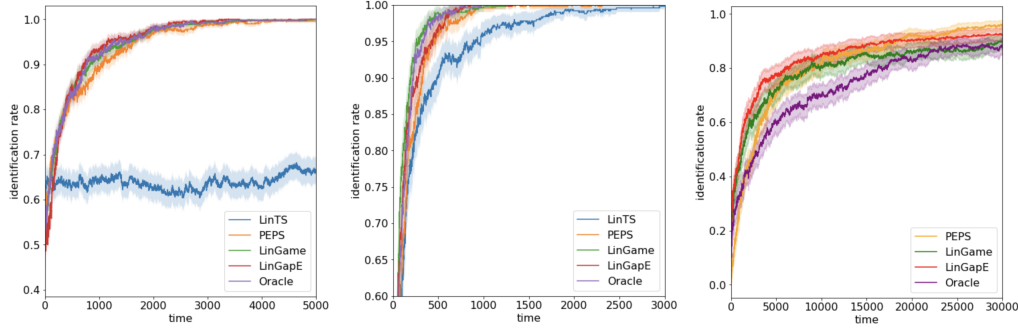


Figure 2: Best-arm identification rate for PEPS, LinGame [7], LinGapE [33], Thompson sampling, and fixed weight strategy under three instances: Soare instance with $\omega = 0.1$, sphere instance with $d = 6$ and $|\mathcal{X}| = 20$, and Top-k instance with $d = 12$ and $k = 3$, with 500 repetitions for each instance. Confidence intervals with plus or minus two standard errors are shown.

	Soare's instance [29]			Sphere			TopK		
δ	0.1	0.05	0.01	0.1	0.05	0.01	0.2	0.1	0.05
PEPS	1027	1606	3284	294	476	794	8618	18193	26118
LinGame	828	1500	2688	186	282	638	8450	>30000	>30000
LinGapE	708	1141	2281	316	433	690	5977	17352	>30000
Oracle	766	1232	2576	243	328	473	16196	>30000	>30000
TS	>5000	>5000	>5000	431	1046	2176	N/A	N/A	N/A

Table 3: The number of samples needed for $\mathbb{P}_{\theta \sim \pi_\ell}(\hat{z}_\ell = z_*) > 1 - \delta$ for various algorithms